

ARSD TECHNICAL NOTE TN-35-04

THE FACT MODEL VOLUME II

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CHEAN PAYA SYSTEMS, SIE.

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ACCOUNT DESIGNATION ASSESSED TO THE RESIDENT

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Summerical Modeling Division, Code 320 // \$7.482001 DATE DECEMBER 1874 NORDA/Naval Oceanographic Laboratory THURS ON BAGE! NSTL Station, Mississippi 167 4 UCH " SHING AGENCY NAME & ACOMESSIE HIllower I from Controlling Office) 18 SECURITY CLASS (of this report) UNCLASSIFIED DECLASSIFICATION DOWNGRADING S CISTRIBUT IN STATEMENT OF this Reports Approved for public release; distribution unlimited 17 DISTRIBUTION STATEMENT (of the aborrect entered in Block 21, if different from Papert) ** SUPPLEMENTARY MOTES Reprinted July 1977 by the Naval Ocean Research and Development Activity. Controlling Office updated in Item 11 above. IS KEY WORDS Caniform on reverse side if necessary and identify by block number) Transmission Loss Ray Acoustics Model Ray Tracing Propagation Loss 20 ABSTRACT (Castimo en reverse elde il necessary and identify by block mamber) The FACT (Fast Asymptotic Coherent Transmission) Model is the new Navy Interim Standard Transmission Model for Ocean environments which may be treated within the context of a single sound-speed profile and a flat bottom. It is a ray-acoustics model designed for the computation of transmission loss as a function of range and frequency at fixed depth. The classical ray treatment has been augmented with higher order asymptotic

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corrections in the vicinity of caustics, and the phased addition of selected paths experiencing significant, predictable coherence effects. The computer program is fully automated requiring only the specification of the environment and the essential parameters.

This report consists of two volumes, the first describing the physics and mathematics contained in the FACT Model as well as comparisons of FACT and normal-mode results. The second vilume describing the program structure and flow with complete samples of input and output Volume I has been distributed to a broad community of both technical and application-oriented users as a Maury Center Report. Volume II his intended primarily for programmers attempting to implement the model on their computers and is being distributed as an AESD Technical Note only to recipients of the FACT program. The complete program listing and punched-card deck will be provided by AESD to qualified users upon request.

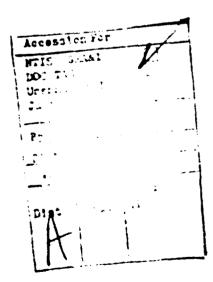


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4. PROGRAM STRUCTURE AND FLOW

This section is divided into four subsections:

- 4.1 Description of inputs
- 4.2 Sequence of calculations
- 4.3 Description of Outputs
- 4.4 Detailed flow charts and descriptions of each of the basic programs and subroutines in the FACT package.

These sections were taken largely from the Ocean Data

Systems, Inc. final report on FACT model development for AESD.*

The basic flow of the FACT model, exclusive of input and output is summarized in Figure 4-1, and is considerably expanded upon in sections 4.2 and 4.3. The complete program listing and punched-card deck are available from AESD upon request.

The objective of FACT is to estimate, by using raytracing techniques, the acoustic transmission loss in a
single-profile, flat-bottom ocean environment, as a function
of range and frequency. Additionally, if requested, FACT
will produce the arrival angles (at the receiver) of
individual ray paths, again as a function of range. Transmission loss (dB re 1 yard) is tabulated in a single array

^{*}C. L. Baker, FACT Transmission Loss Model Development for Acoustic Environmental Support Detachment - Final Report, Ocean Data Systems, Inc., June 30, 1973 on Contract N00014-73-C-0131.

of dimension 250x6 at up to 250 equally spaced range points for each of one to six frequencies. Arrival information is written to an auxiliary (tape or disk) file as individual records containing fields for range, angle, and intensities at up to six frequencies.

As indicated in the documentation included as part of the FACT Handout, the primary component of the FACT Package is a single subroutine FACTTL, which may be incorporated into any of a number of complete programs requiring an estimation of transmission loss versus range and frequency. One example of a stand-alone program is included: TLOSS, a program which reads input parameters from cards, calls on FACTTL for losses, and prints and/or plots the results. This program is primarily useful to analysts requiring a small number of runs as part of a design program on a demand basis.

Two additional transmission loss models may be used to supplement FACT in those cases where a full FACT solution is liable to result in excessive running times. These models, SHALTL and HFCHTL, are designed specifically to approximate the results of a complete FACT solution in shallow-water transmission and half-channel transmission respectively. Subroutine HFCHTL is an integral component

of FACTTL in that the output of HFCHTL is supplemented by the output of FACTTL for the direct and bottom-reflected paths. On the other hand, in order to employ subroutine SHALTL a modification to TLOSS is required (e.g., replacing the call to FACTTL by a call to SHALTL). Care should be exercised in using both of these models as both serve only as quick-running alternatives to the normal FACT processing. Additionally, the HFCHTL model requires further care in use in that it is valid only for the specific frequencies and source/receiver combinations contained within the listing.

The documentation which follows is designed to supplement the user-oriented material presented in the FACT Handout. It is intended for computer programmers, and is primarily concerned with the overall structure and interrelation of the various components of the FACT Package. The organization of this material follows that of the FACT programs components is presented in Section 4.4.

The PACT model itself, written entirely in FORTRAN IV, is invoked by a single call to subroutine FACTTL. Core requirement, excluding input and output, but including all other FACT and system computational routines, is approximately 8,400 decimal (20,300 octal) cells on the CDC 6400/6600.

4.1 Inputs

The inputs to FACT are primarily geometrical and environmental in nature. They are:

- A sound velocity profile: the speed of sound is specified at each of up to 50 points from the surface to the bottom. Depth/velocity pairs are in feet and feet per second or meters and meters per second.
- Surface and bottom conditions: wave height in feet; FNWC bottom class.
- . Source and receiver positions: depths in feet.
- . Frequency information: frequencies in Hertz; coherency flags.
- . Range information: number and spacing of range points in nautical miles.

4.2 Sequence of Calculation

In the following presentation, only the most significant steps in determining transmission loss are outlined; many computational steps, such as the calculation of constants and other factors essential to the calculation are covered in detail in the sections dealing with individual subroutines. Some liberties have been taken in describing the sequences of calculations, but it is essentially as follows:

- Profile correction: The profile points are corrected to take account of spherical earth geometry. Note that depths and depth indices are often used interchangeably (as appropriate) in discussing FACT.
- Axis location: The deep sound channel axis, if any, of the profile is located, and, under certain conditions the source and receiver depths are altered to allow simulation of axis-to-axis transmission.
- Profile augmentation: The source and receiver depths are inserted in the profile as explicit points, altered slightly, if necessary, to avoid equal velocities at the two depths.
 - Source selection: For the remainder of the FACT calculations, the source and receiver depths are selected from the two depths of interest by assigning the depth with the lesser sound velocity as the source depth -- the starting point for the ray tracing process. The index of this point in the profile, Ki, is used heresiter to designate the source (or source depth); the other index, K2, is used to designate the receiver or receiver depth. (Care is taken to distinguish the "true" source from the ray-tracing source where the distinction is important.)

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- Geometry factors: A number of flags are set (at various points throughout the program) to indicate various geometrical relationships between source and receiver.
- Low-frequency effects: The WKB phase factors for low frequency cutoff are calculated.
- Ray selection: The angles of the rays to be traced from K1 to K2 are selected, grouped into one or more families. The selection is based on the velocity profile, source, and receiver depths.

 Rays are chosen so that within each family, an analytical fit of Range versus Angle can be made, thus smoothing and retaining legitimate caustics while removing false caustics; the functional form of the fit will vary with family type. If the profile and associated source and receiver depths lead either to more than 20 families or 100 rays, processing is terminated and the transmission loss array is returned with zero values for all entries.
- Ray tracing notes: Because the environment is single profile, flat bottom, any ray which is traced exhibits a periodicity over the range of interest and is actually traced for only a single such cycle.

^{*}Wentzel-Kramers-Brillouin approximation - see L. M. Brekhovskikh, Waves in Layered Media, Academic Press, New York, 1960b, pp 452-3.

Within a single period, each ray angle selected may represent one, two, or four paths (arrivals) from source to receiver, per period, depending upon the geometry involved: the source angle may be positive, negative, or both, and may either he reflected or refracted at the receiver, or may cross and re-cross the receiver depths. Eacl. arrival is assigned a number, termed the arrival order, indicating the number of deep cycles which the ray has undergone; arrival order corresponds to the direct path. The ordering of arrival ranges within a single period or cycle of a ray, and the assignment of these ranges (plus multiples of the period) to individual arrival orders is determined and controlled by a number of flags and indices which are detailed elsewhere.

Path combinations: Depending upon the geometries involved, two or four paths from the source to the receiver may be combined into a single path of doubled or quadrupled intensity. This may happen for instance, if the source is so close to the surface that the downgoing ray and the surface-reflected upgoing ray are essentially parallel and arrive at the receiver at essentially identical angles. A similar geometry may apply at the receiver, or at

both the source and receiver. The processing of such combined rays is controlled by several flags indicating the simplified situation.

- Family processing: Each family, in turn, is processed to determine its contributions to the total intensity arising from the source, and equivalently, overall transmission loss. At the same time, individual arrival angles and intensities are written to a separate file for later processing. This loop on families is the major processing loop in FACT- Within each family, the zeroorder or direct path is processed first. This is followed by a loop in which subsequent orders 1, 2, 3,... are processed in turn. There is no fixed limit on the number of orders which FACT may be required to process; this loop is terminated only when significant intensity no longer is being contributed by any path within the family at the ranges of interest.
- Half-channel note: When a half-channel case has been flagged on input, only the direct and bottom and surface-reflected arrivals are processed as outlined above. In these cases, the non-direct path, non-bottom and surface reflected contribution to intensities are approximated and added by a separate half-channel model.

Final processing: When all families have been processed, surface-duct contributions, if present, are added to those intensities already calculated, and then converted to transmission losses (re one yard).

Processing of an arrival order of a family of rays consists of the following steps:

- . The arrival ranges for each of the (one to four) paths with this order are calculated.
- . For each wath, the coefficients and parameters required to express range as a function of ray angle are calculated. Any one of four possible functional forms is used according to family characteristics.
- If the range intervals for all four paths exceed the maximum range of interest, processing of arrival orders for the family is terminated.
- Subroutine INSTOR (or CUSP if applicable) is called to calculate and add the intensity arising from each (smoothed and fitted) path to the transmission loss array at each range point for each frequency.
- If the intensities from all four paths drop below a specified minimum value, processing of arrival orders for the family is terminated.

Processing of one path of an arrival order by INSTOR or CUSP consists of the following steps:

- to determine whether or not a caustic exists, and to find the minimum and maximum ranges at which contributions to total intensity are made.
- . If this range interval is beyond the range of interest, processing of the path is terminated.
- At each applicable range point, the number of arrivals

 (rays) is calculated: zero indicates the shadow

 zone of a caustic, one or two indicates an illuminated region.
- the intensity contribution from each ray is added to the transmission loss array for each frequency at the range being processed. The intensity is computed as an analytic function of range, frequency, and the values of ray angle and the derivations of range with ray angle at this range; the latter are obtained by examination of the range versus ray angle fit.
- The calculated intensities are modified, if required by factors reflecting coherent, semi-coherent, or incoherent path addition, shadow-zone fall-off, low-frequency cutoff effects, and bottom-bounce losses as applicable.
- . If flagged, range, arrival angle, and intensity information is written to an external file.

When all range points have been processed, a flag is set to indicate if the minimum range of the path has exceeded the range of interest, or if the contribution to intensity has dropped below a specified minimum value.

4.3 Outputs

The primary output from subroutine PACTTL is an array, TL, of dimension 250x6, giving transmission loss (in dB re 1 yard) at each of the range points and frequencies specified as input parameters. If the ray selection process results either in too many rays (> 100) or too many families (> 20), a two-line message will be printed indicating this condition, and the TL array will contain 20x03 at the specified ranges and frequencies.

If, in addition, arrival information is desired, the immediate results arrival records should be written. The format of these records is detailed in the description of subroutine INSTOR.

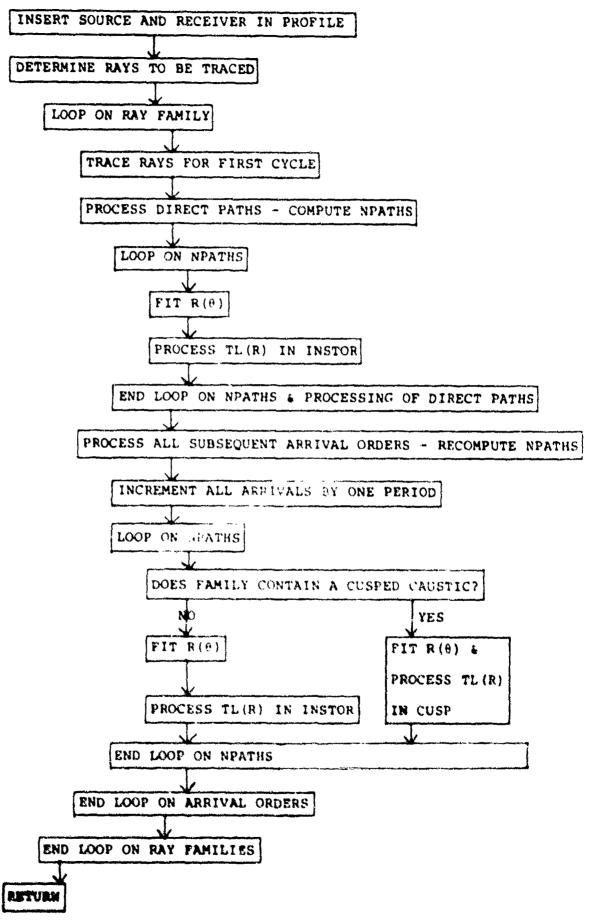
The output file is never positioned nor are any file marks written; these functions are delegated to the calling program.

Optional debugging output is also available via an input parameter; care should be taken in setting this flag, as the potential exists for many hundreds of pages of output from a single run.

4.4 Components of the FACT Package

This section consists of a description of each of the components of the FACT Package -- the driver programs, the main computational routine, and auxiliary subroutines and functions. For each of these, the following material is included:

- . A brief description of the function of the component in the Model.
- . Equations used by the component when these are not immediately evident from the function of the component and/or the program listing.
- . Parametric and common input and output variables.
- . Flow charts, expressed in physical terms to the greatest extent possible, for the major programs and routines of the Model.
- . Additional material, as applicable, to present the details of the program logic not included in the flow charts for the routine.



Pigure 4-1. COMMITTED OF PROGRAM-PROM IN PACEPUL

PROGRAM TLOSS

TLOSS is the driver which reads card inputs, invokes

FACTL to compute transmission loss (and arrival structure) versus

range and frequency, and prints and/or plots the results.

CARD INPUTS

The card input formats and sequence are detailed in the FACT Handout, pages 5-9 through 12. See also subroutine RDPROF, page 4-17.

PRINTED OUTPUTS

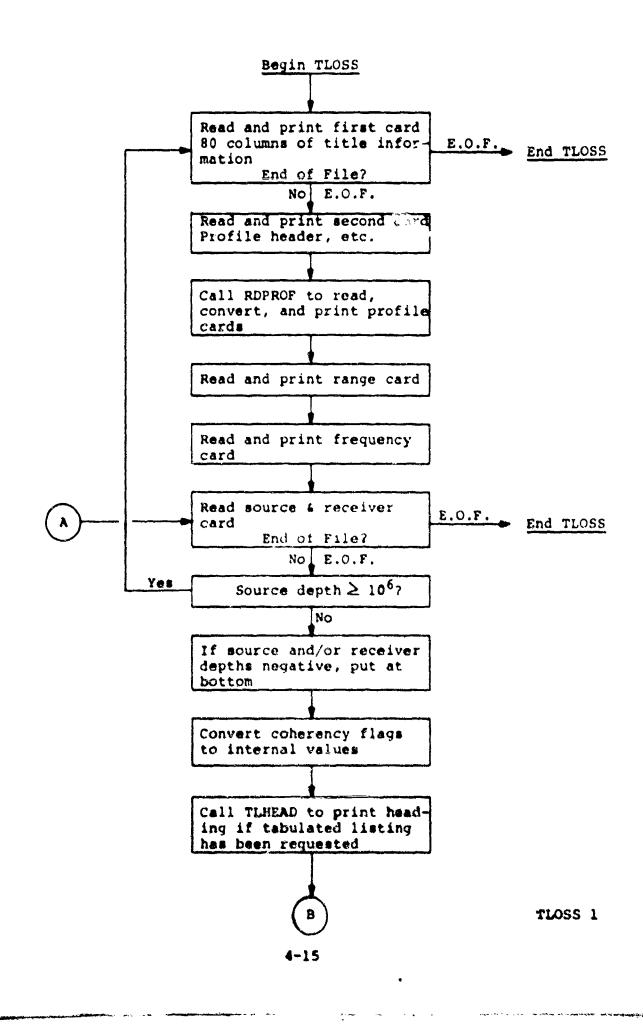
The formats for tabulated and plotted printer outputs are detailed in the FACT Handout, pages 5-14 through 33. See also subroutine TLHEAD, and PLOTTL, pages 4-19 and 20. TLOSS also prints the data on the input cards as they are read.

COMMON USAGE

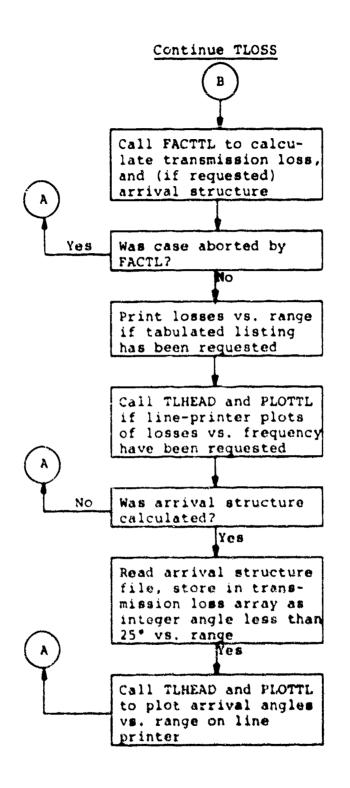
None

NOTE

A complete FGRTRAN listing of TLOSS is included in the portion of the FACT Handout included in this report, pages 5-43 through 47.



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SUBROUTINE RDPROF

RDPROF is called from TLOSS to read profile data from cards, and convert, if necessary, to FACT units. Card formats are detailed in the FACT Handout. Input data is printed as it is read; see pages 5-14, 5-23 and 24, and 5-33.

PARAMETER INPUT

N i No. of Profile Points

CARD INPUTS

- A) N Positive:
 - Z Profile Depths (4/Card), meters or feet
 - C Profile Velocities (4/Card), mtrs/sec or ft/sec
- B) N Negative:
 - D Profile Depths, metars
 - Profile Temperatures, degrees Centigrade
 - S Profile Salinities, parts/thousand

PRINTED OUTPUTS

The data read from cards is printed along with the results of any conversions performed. One of three applicable formats is used:

- 1) Depths in feet and velocities in feet per second.
- Depths in meters and velocities in meters per second,
 plus depths in feet and velocities in feet per second.
- 3) Depths in meters, temperatures in degrees Centigrade,

RDPROF (Cont'd)

salinities in parts per thousand, plus depths and and velocities as in 2).

PARAMETER OUTPUTS

- Z Array (50) of Profile Depths, feet
- C Array (50) of Profile Velocities, ft/sec

COMMON STORAGE

None

SUBROUTINE TLHEAD

TLHEAD is called from TLOSS for the purpose of printing any of three different heading formats; these are detailed in the FACT Handout.

PARAMETER INPUTS

TITLE	80 Character Title (8 words, 19 char/word)
S	Source Depth, feet
R	Receiver Depth, feet
IF	Array (6) of Frequencies, Hz
JC	Array (6) of Coherency Plags, (0,1 or 2)
IX	Array (6) of Characters to be Used for Plotting
NF	No. of Frequencies
ĮTYP	Heading Type, 0,1,2

PRINTED OUTPUTS

A) ITYP - 0:

Page Heading for Tabular Transmission Love vs. Range

B) ITYP = 1:

Page Heading for Plot of Transmission Loss vs. Range

C) ITYP = 2:

Page Heading for Plot of Arrival Angle vs. Range

COMMON STORAGE

Non-

SUBROUTINE PLOTTL

PLOTTL is called by FACTTL for the purpose of plotting, using the line printer, either transmission loss versus range or arrival angle versus range. The plot format, examples of which appear in the FACT Handout, consists of an array of printer positions 121 columns wide and 51 columns high, augmented by horizontal and vertical scale information. Input is taken from an array, TL, of dimension 250 (range points) by 6 (frequencies or angles). Up to 250 range points and up to 6 frequencies or angles may be plotted. Either a separate (input) or a single (default) plotting character may be used for each frequency or angle; this is controlled by flag IX. Alternate range points only are plotted when the number of range points exceeds 120. MNDB is the minimum value of the plot: If greater than zero, the abscissa values increase downward from MNDB to MNDB + 50; if less than zero, the abscissa values decrease downward from ABS(MNDB) to ABS(MNDS) - 50. The units of the incremental range, DR, are arbitrary, but such that the maximum range is 9999.9 (nm) or less.

PARAMETER INPUTS

NR Number of range points, \$250

DR Incremental range, nautical miles

NF Number of frequencies, ≤ 6

IX Array (6) of plotting characters; or zero

MNDB Minimum value of output plot, dB or degrees

TL Array (250,6) of values to be plotted, dB or degrees

PLOTTL (Cont'd)

PRINTED OUTPUT

Line printer plot of the values in TL as a function of range, with up to six plotted values at each of up to 120 range points.

COMMON STORAGE

一名 多数的工作的连续

None

SUBROUTINE FACTTL

range. All input and output is directed by the values of the parameters of the call to FACTTL; the common storage of FACT and its subroutines must be kept separate from that of any calling routine. A condensed description of the major processing done by FACTTL is found on pages 5-5 through 7.

PARAMETER INPUTS

YS Source depth, feet

YR Receiver depth, feet

FREQB Array (6) of frequencies, Hz

IC Array (6) of coherency flags; 0,1 or 2

WHF Wave height, feet

IB FNWC bottom type, 1-9

NPTSPP No. of points in sound velocity profile, ≤ 50

II. Index of surface layer in profile, ≤ 50

YPP Array (50) of profile depths, feet

CPP Array (50) of profile velocities, feet per second

NR No. of range points, ≤ 250

DR Incremental range, feet

IARVTP File unit for arrival output if ≠ 0

IP Debugging print flag, 0 or 1

FACTTL (Cont'd)

PARAMETER OUTPUTS

TL Array (250,6) of transmission loss vs. range and frequency, dB

FILE OUTPUT

Unit IARVTP One record for each arrival angle at each range point, including path loss vs. frequency.

(See INSTOR for format, page 4-79)

COMMON VALUES CALCULATED

CONTION TABLE	ab cyabeo artab	<u> </u>
/RANGEL/	NRANGE	No. of range points (≤250)
	nfreq	No. of frequencies (≤ 6)
	IFQMIN	Index of lowest frequency ≤ 6
	FREQ	Array (6) of (radian frequencies)**-1/3
	FREQK	Array (6) of frequencies in KHz
	RANGE	Array 2000 of range values, feet
/FLAGS/	IGTYP	Type of family being processed 1-4
	THMIN	Angle giving minimum range in fit, Rad
	THMAX	Angle giving maximum range in fit, Rad
	CONST	Const*(Receiver Velocity)**1/3
	clc2	Ratio of source depth velocity/
		receiver depth velocity
	CBC2	Ratio of bottom velocity/receiver
	1	depth velocity
	ICOH	Flag to indicate combination of arrivals, 0-3
	IRSR	Flag to indicate surface reflection
	NBOT	No. of bottom reflections

FACTTL (Cont'd)

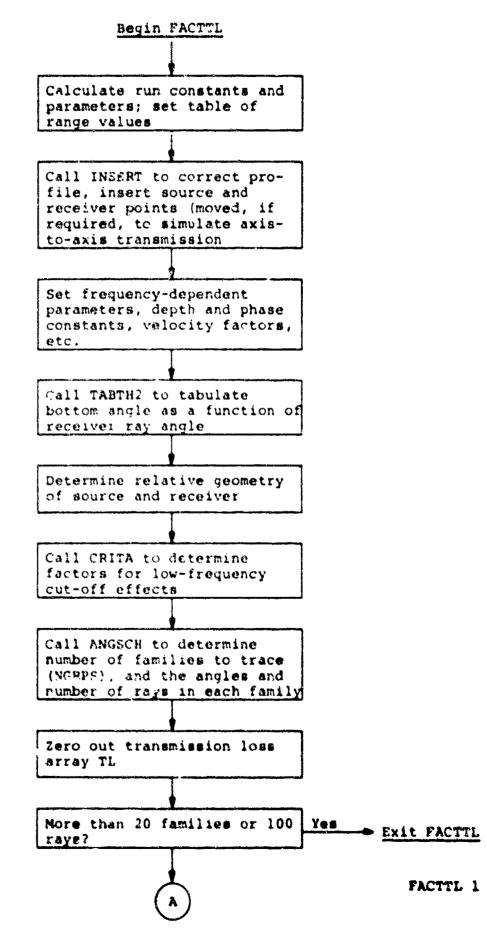
	IBTYP	PNIM? hottom tune
		FNWC bottom type
	IFLAG	Array (6) of coherency flags
	DK	Array (2,6) of semi-coherent phase factors
/RAYZER/	IREFRZ	Flag indicating grazing family
	THETMB	Critical angle for bottom type, radians
	THBINC	Incremental angle for bottom rays, radians
/INIT/	A K	Vertex velocity of ray to be traced
	SINTHO	Sine of initial angle of ray to be traced
	IML	Index of mixing layer in input profile
/INPUTS/	IRAY	Number of rays (in TH) in family being
		processed (≤100)
	KP	Index (in R) of arrival being processed
		(1-4)
	NP	Index of path being processed (1-4)
	NORDER	Arrival order being processed
	NG	Index of group (family) being processed
		(≤20)
	IPAR	Flag for type of family being processed
		(1 or 2)
	R	Array (100,4) of arrival ranges vs. angle
		and arrival, ft
	TH	Array (100) of ray angles in family
		being processed, rad
/FITS/	THF	Array (3) of angles of fit of R vs. 0
	A	Array (5) of coefficients of fit

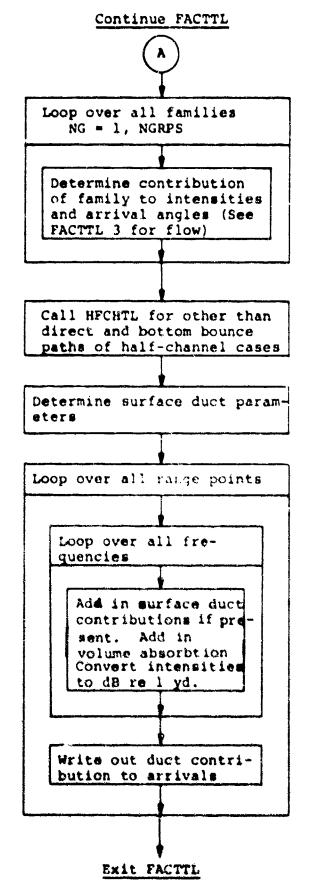
FACTTL (Cont'd

	XMIN	Ordinate value for min value of fit
	XMAX	Ordinate value for max value of fit
	RMIN	Minimum value of range in fit
	RMAX	Maximum value of range in fit
	RANMIN	Minimum range value to be fit
/CUSPCM/	CCUSP	Velocity at cusp depth, ft/sec
/AUTCOH/	FNMIN	Min no. of range pts/surf image cycle = 8/3
	FNMAX	Max no. of range pts/surf image cycle = 6
	FNXI	Reciprocal of FNMAX-FNMIN
	FNCYC	Array (2,6) of cycles of phase difference

NOTE

Following the flow charts for FACTTL, additional pages are presented which elaborate on the geometry of the ray paths which are used in the FACT trans of the line calculation, and the values of flags and indices required to sequence the corresponding path ranges as a function of family, arrival order and path index.



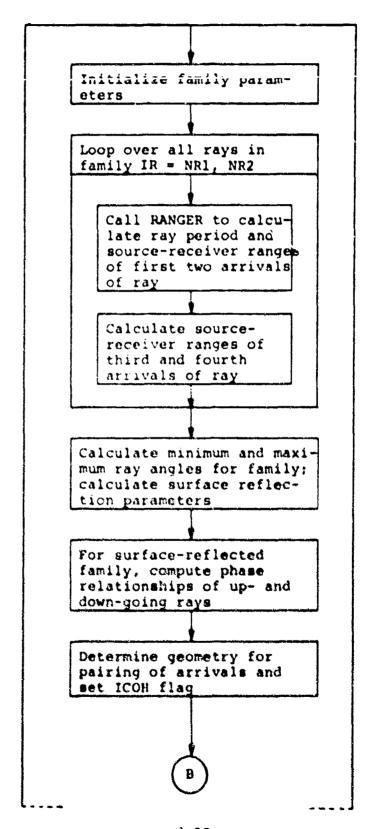


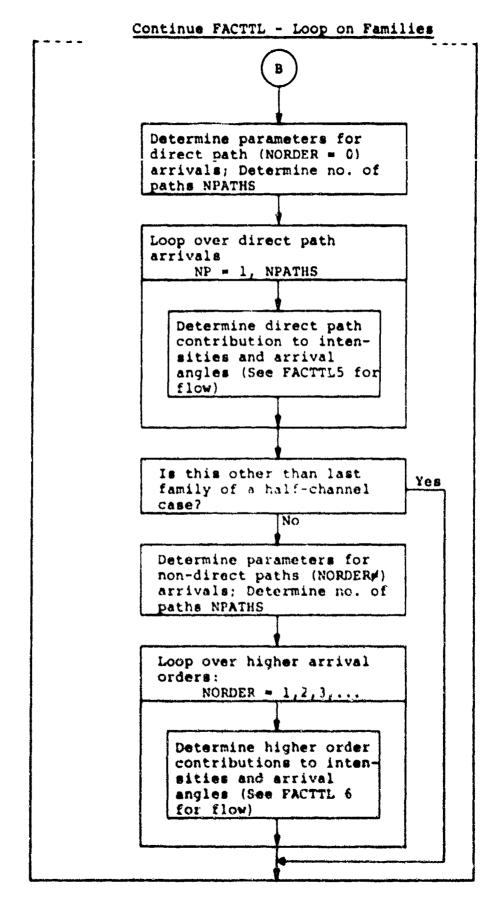
FACTTL 2

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FACTTL - Loop on Families

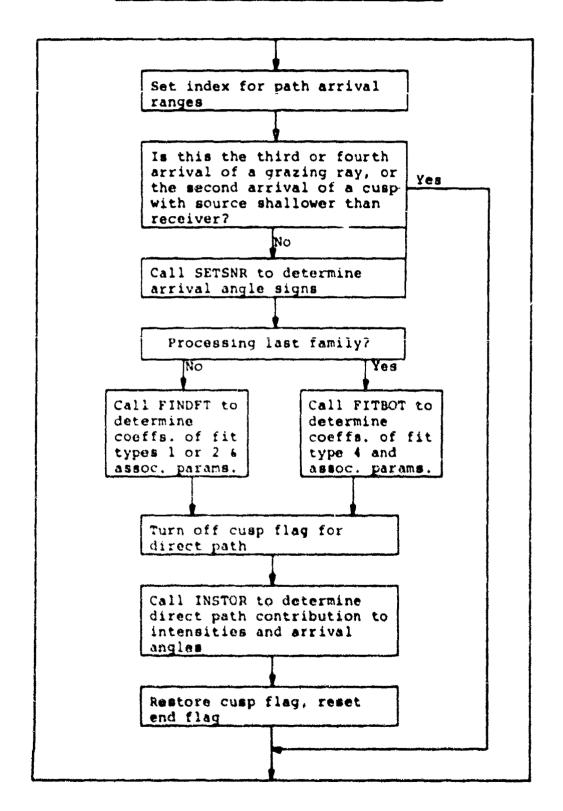
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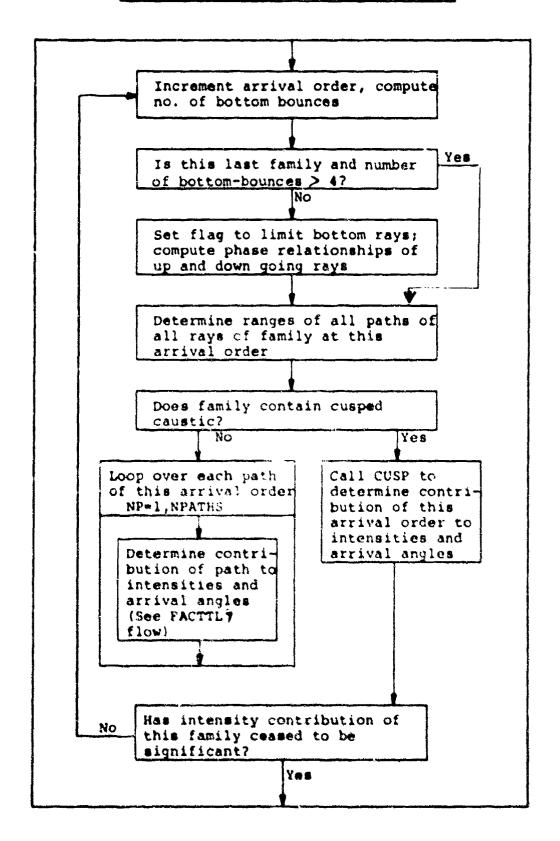


Section 1997 Section 1997

FACTTL - Loop on direct path arrivals

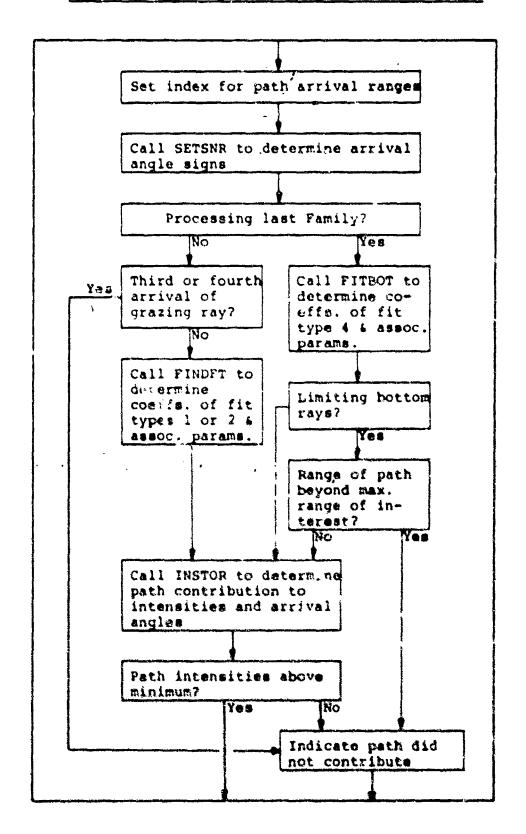


FACTTL - Loop on higher arrival orders



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FACTTL - Loop on paths of higher arrival orders

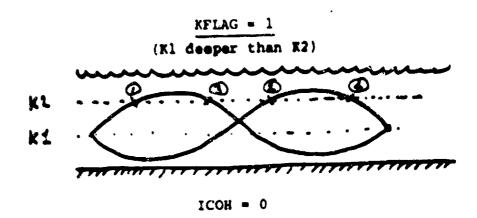


	sot	URCE DEPTH -	K1
RECEIVER DEPTH-K2	AT SURFACE	IN Between	on Bottom
at Surface		4	7
in Between	2	1	3
on Bottom	6	5	

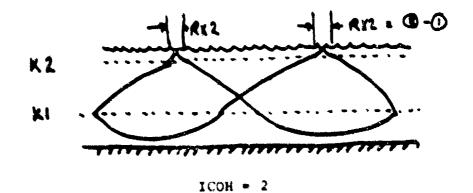
FACTTL - Setting Of Geometry Indicator KFLAG

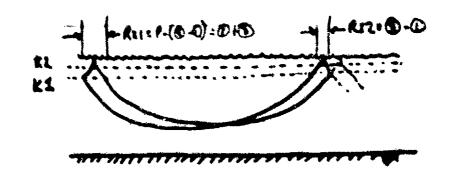
		X	NORDER - 0			NOPDER - 1, 2,	 	
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K2 BOTTOM	0	2	00	0	2	00	0 0	1
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K1 SURFACE S: K2 BOTTON	o	-4	Θ	0	-	9	1	1
K1 BOTTON 1: K2 SURFACE	0	7	- (i)	0	7	0	1	•
								1

FACTTL - Indices for Determination of Arrival Ranges (), (2) etc. refer to path subscript values in R (angle, path) erray



(ICOH = 1 NOT POSSIBLE)

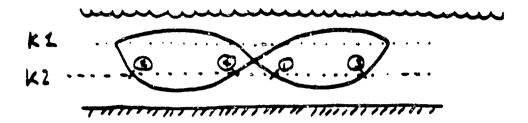




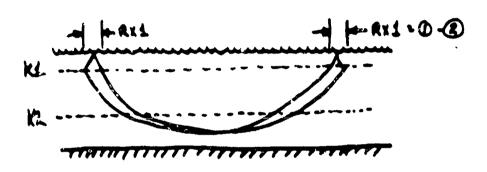
1COH = 3

FACTTL - Coherence Geometry for Combining Ray Paths 1 of 8

KFLAG = 1 (K2 deeper than K1)

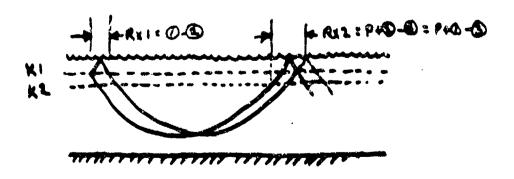


ICOH = 0



ICOH = 1

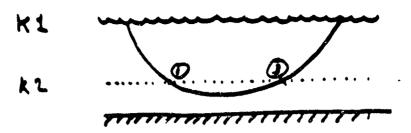
(ICOH = 2 NOT POSSIBLE)



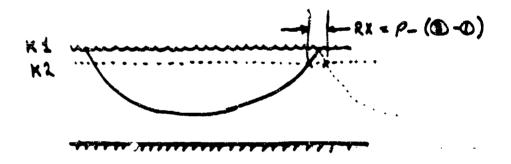
ICOH = 3

FACTTL - Coherence Geometry for Combining Ray Paths 2 of 8





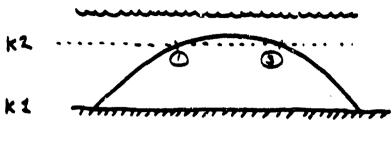
ICOH-= 0



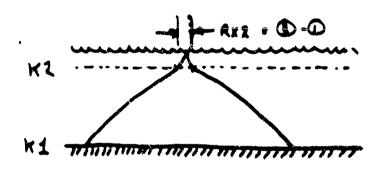
ICOH = 2

PACTTL - Coherence Geometry for Combining Ray Paths 3 of θ

KFLAG - 3

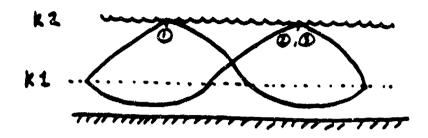


ICOH = 0

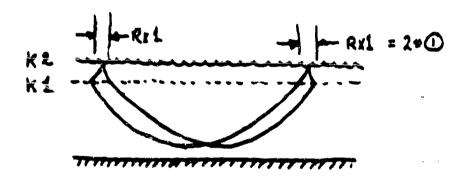


ICOH = 2

FACTTL - Coherence Geometry for Combining Ray Paths 4 of 8

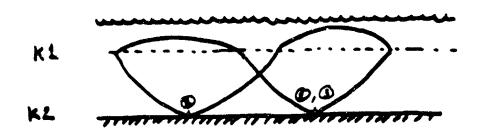


ICOH = 0

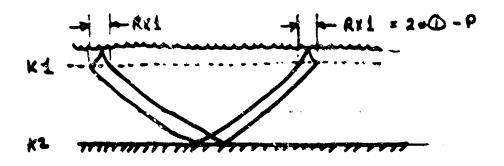


ICOH = 1

FACTTL - Coherence Geometry for Combining Ray Paths 5 of 8



ICOH = 0



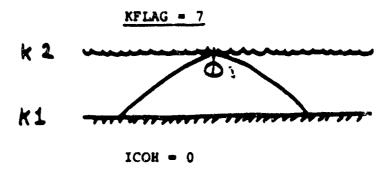
ICOH = 1



K2 Transmitterransmitter

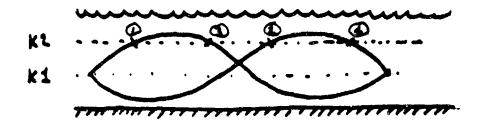
ICOH = 0

PACTTL - Coherence Geometry for Combining Ray Paths 7 of 8



FACTTL - Coherence Geometry for Combining Ray Paths 8 of 8

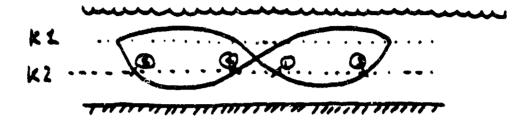
 $\frac{\text{KFLAG} = 1}{\text{(K1 deeper than K2)}}$



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Jorden	NA	0	2	3
0	1	6	0	Θ
	2	D	_	
1	1	3	©	(3)
	2	•	D+P	_
	3	0 +P		_
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2	1	(3) + P	20+0	3 +P
	Ž.	Ð + P	D+1.P	_
·	3	0 +2 P	_	-
	4	(3) +2.P	_	
3	1	\$ +2.P	3+2·P	(Z)+2.P
	2	0 + 2.P	D+3.P	_
1	3	0+3.P		
	4	Ø + 3.P		

FACTTL - Ray Path Range Selection 1 of 8

KFLAG = 1
(K2 deeper than K1)



		ordern for I	OF RAMI	
HOLDER	NP	0	1	3
٥	1	(2)	3	(3)
	2	D	~	
1		(b)	(3)	©
	2	3	5 + P	-
	3	Ø + P	_	-
	4	0+6		C++
2	1	Ø + 0	1 + P	(D+P
·	2	(D) + P	Ø+2.P	_
	3	Q + 2.P		
	4	O +2.0	-	-
3	1	@+2.P	1 +2.P	3+2.P
	2	O + 2.P	Ø+3.P	_
	3	Ø+3.P	_	•
	4	Q+3.P	****	**

FACTTL - Ray Path Range Selection 2 of 8

ete

KFLAG = 2

ALEGASTICAL .

K1 P

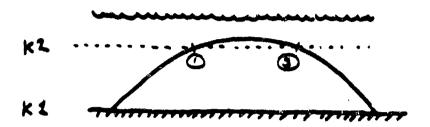
mmmmmmmm

. 1,080 (\$18).

		Ti .	LOH VALUES
USEREL	NP	0	1
0	1	0	0
1	1	0	3
	2	() + P	_
2	1	(3) + P	Ø+P
	7.	10+21	_
3	1	3 + 1.0	B +2.8
	2	Q +3.P	_
etc.		•	.te

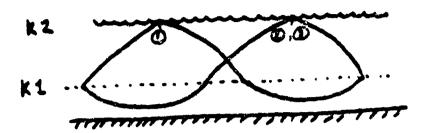
PACTTL - Ray Path Range Selection 3 of 8

KFLAG = 3



0 0 0 0 0 0	0 · p
① ②	_
0	_
0 + 1	0 .0
· ·	0 + 0
1+ 4	-
D + 2.P	0 +2.1
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D+3.P	
	D+3-1 D+3-1

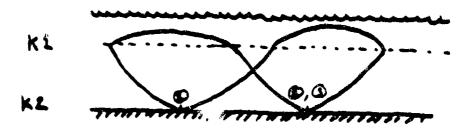
FACTTL - Ray Path Range Selection 4 of 8



		O L DELING	or Ravers OH VALUES
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0	1	0	Φ
1	1	0	©
	2	0 + P	
2	1	2	(D) + P
	2	10 +2 8	-
3	1	3 +2.0	(D+2.P
	2	1 +3 P	

FACTTL - Ray Path Range Selection 5 of 8

KFLAG = 5



		5 4	of Rowers Values
Meter	UP	0	1
o		0	3
	2	0	
1	1	3. + 6	0+0
	2	0+0	
2	1	3 + 20	1+2.P
	2	10 +20	ignada .
3		1.430	Q+3.P
	1	(£) + 3.P	_
Q.	Àv.		de

FACTTL - Ray Path Range Selection 6 of 8

KFLAG = 6

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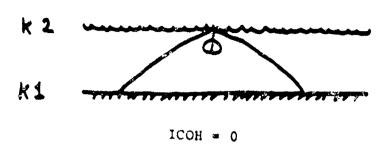
K2

ICOH = 0

NORDER	NP	Olyena or Ranges
0	1	0
1	1	0+6
2	1	0+2·P
3	1	6+3.6
+	1	W+4.P
5	*	Ø → S.P
<u>- 1</u>	\	

FACTTL - Ray Path Range Selection ? of 8





MORDER	NP	ORDERING OF RANGES
0	1	©.
t	1	O+0
2	1	U+2.P
3	1	Ø +3·P
4	1	O+4.P
5	1	O+5.P
! e1	اد	a.fc

FACTTL - Ray Path Range Selection 8 of 8

SUBROUTINE SHALTL

SHALTL is a self-contained model for estimating shallow-water (less than 1000 feet) transmission loss for bottom-class/frequency combinations permitting perfect reflection of rays at grazing angles on the bottom less than some critical angles. A trivial modification to TLOSS will cause SHALTL to be called in place of FACTTL for these combinations which may be followed for a call to FACTTL for the remaining cases. Note that a single frequency is processed by each call to SHALTL.

SHALTL assumes a homogeneous (uniform sound velocity) medium and includes an average surface image interference effect. A simplified bottom-loss approximation assumes a bottom which is perfectly reflecting to a critical angle THCDG. Above this angle, the bottom has a constant loss FL90 for the first order path and is perfectly absorbing for higher order paths. The constants THCDG and FL90 are chosen from 3x3 arrays as a function of bottom type (1-3) and frequency band (0-150 Hz, 151-699 Hz, and 700-1000 Hz).

PARAMETER INPUTS

YS Source depth, feet

D Bottom depth, feet

YR Receiver depth, feet

NR No. of range points, <250

P Prequency, Hz

DR Incremental range, feet

IB Bottom type, 1-3

SHALTL (Cont'd)

PARAMETER OUTPUT

TL Array (25-)) of transmission loss versus range,
dB re l yard

SUBROUTINE INSERT

INSERT is called by FACTTL at the beginning of each case to process the input sound velocity profile. INSERT corrects all depths and velocities to account for spherical-earth effects, and ensures that explicit points for source and receiver depths are inserted in the profile and that they are at points of unequal sound velocity. Prior to inserting these source and receiver depths in the profile, INSERT calls AXIS to account for axis-to-axis transmission; this call may result in the source and receiver depths being changed. For ray-tracing purposes, INSERT chooses, from these two depths, the point with the lesser sound speed as the source for raytracing purposes; throughout the remainder of the FACT program, the term source refers to this point. Three indices are set by INSERT as the result of this processing: Kl, the index of the ray-tracing source; K2, the index of the ray-tracing receiver; and KRC (=1 or 2) indicating which of these is the depth at which arrival angles are to be calculated.

INSERT constructs the final sound velocity profile in common area /VELOC/ and the gradients of this profile in common area /GRADS/.

PARAMETER INPUTS

- Yl Source depth, feet
- Y2 Receiver depth, feet
- NPTS No. of points in sound velocity profile ≤ 50

INSERT (Cont'd)

YX Array (50) of profile depths, feet

CX Array (50) of profile velocities, feet per second

IPRNT Debugging print flag

COMMON INPUTS

/INIT/ IML Index of mixing layer in profile YX,CX

PARAMETER OUTPUTS

Yl Corrected source depth, feet

72 Corrected receiver depth, feet

KRC Flag indicating arrival angle depth

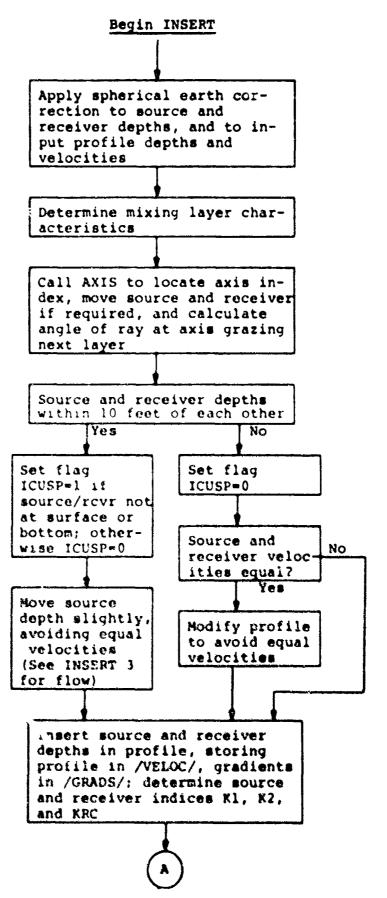
COMMON OUTPUTS

/VELOC/	NPTSP	No. of points in temporary
	YPP	Array (60) of corrected profile depths, feet
	CPP	Array (60) of corrected profile velocities,
		feet per second
/GRADS/	G	Array (60) of profile gradients, (sec)
/INIT/	к1	Index of ray tracing source in corrected
		profile
	K2	Index of ray tracing receiver in corrected
		profile
	YML	Mixing layer depth in corrected profile
	IMLP	Index of mixing layer in corrected profile
	Gl	Gradient above mixing layer in corrected
		profile
	G2	Gradient below mixing layer in corrected
		profile

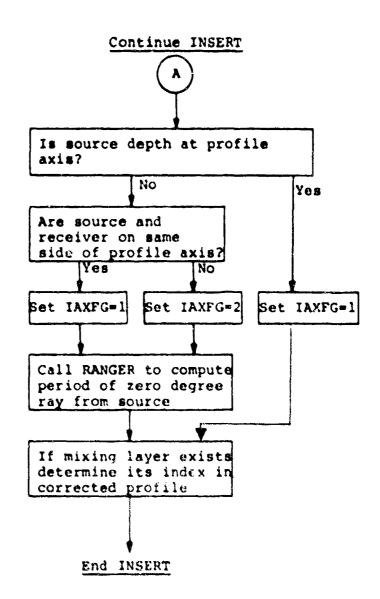
INSERT (Cont'd)

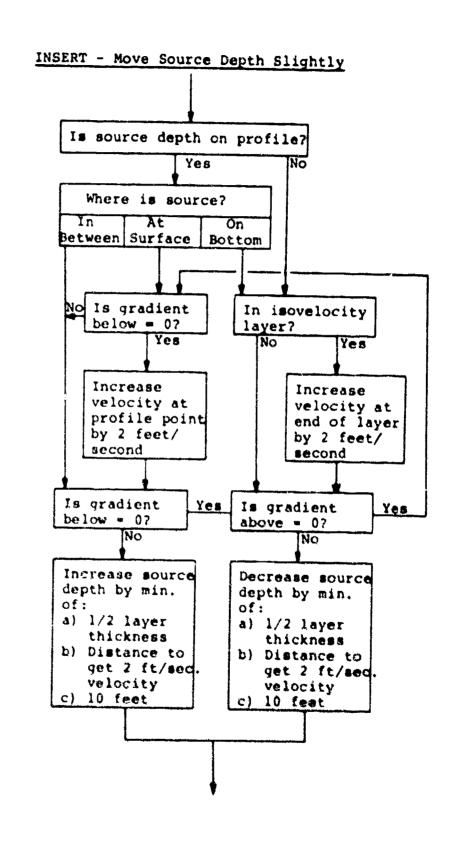
/CUSPCM/	ICUSP	Cusped caustic flag
/PERIOD/	PERO	Period of zero degree traced from Kl
	IAXFG	Plag indicating source-receiver-axis
		geometry
	COSA	Limiting ray angle (at axis) for analytic
	ANGP)	low frequency cutoff, and its cosine

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INSERT 1





SUBROUTINE AXIS

AXIS is called from INSERT to determine the parameters required to handle axis-to-axis transmission. Initially, the deep sound channel axis is located (if present) and the smaller of the two velocities immediately to either side of the axis is obtained. This information is used to fit a smooth (quadratic) function to the velocity profile which is continuous in velocity and gradient at the axis. The period of the zero-degree ray at the axis is then determined as an analytic function of the smoothedprofile coefficients. Subsequently, the angle of the ray which has the same period in the linearly-segmented profile is determined by means of a simple closed-form expression. If the two turning-point (vertex) depths of this ray about the axis bound both the source and receiver depths, then the source and receiver depths are required to take on the depth value of one of the turning points.

When no axis exists, the "axis" depth index is set either to the surface or to the bottom, and the period of the zero degree ray (PERO) is set to 0.

Following the above calculations, AXIS determines the limit angle for analytical low-frequency cut-off effects. This angle is the angle of the ray at the axis which just grazes the next layer in the velocity profile.

AXIS (Cont'd)

PARAMETER INPUTS

YS Source depth, feet

YR Receiver depth, feet

IPR Debugging print flag

COMMON INPUTS

/VELOCX/ NPTS No. of points in sound velocity profile
Y Array (60) of profile depths, feet
C Array (60) of profile velocities, ft/sec

PARAMETER OUTPUTS

YS Adjusted source depth, feet

YR Adjusted receiver depth, feet

COMMON OUTPUTS

/PERIOD/ YUP* Minimum depth of axis ray, feet
YDN* Maximum depth of axis ray, feet
PERO Period of axis ray, feet
COSA Limit angle at axis for analytical
ANGP low-frequency cutoff, radians, and its cosine
LX Index of axis in profile

*LX # 0 or NPTS only

SUBROUTINE TABTH2

TABTH2 is called by FACTTL to tabulate the ray angle at the bottom, $\theta_{\rm B}$, as a function of the ray angle at the receiver depth, $\theta_{\rm K2}$. Twenty-one equally-spaced values of $\theta_{\rm K2}$ are tabulated, from $\theta_{\rm Min}$ to W/2, along with the corresponding (unequally-spaced) values of $\theta_{\rm B}$. The value of $\theta_{\rm Min}$ is that of the first ray which touches the bottom. For ease in interpolation (by function THBOT), the ratios of the corresponding increments in the two tables are also tabulated.

PARAMETER INPUT

CBC2 Ratio of bottom velocity to receiver depth velocity

COMMON OUTPUTS

/TH2TAB/	TH2MIN	Minimum ray angle at receiver depth
	FACTOR	Reciprocal of increment in Θ_{K2}
	TH2T	Array of 21 values of θ_{K2}
	THBT	Array of 21 values of θ_{B}
	RATIO	Array of 20 ratios of $\Delta \Theta_{\rm p}/\Delta \Theta_{\rm wg}$

SUBROUTINE CRITA

CRITA is called by FACTTL to compute the WKB phase factors for low-frequency cutoff effects. The deep-sound channel is first located (as in subroutine AXIS), and subroutine RAYT is called to compute the relative phase of the ray along the axis with initial angle such that the next layer in the profile is just grazed (this is the limit angle for analytical cut-off effects which was calculated by AXIS) CRITA then determines the relative phases for each frequency being processed, using analytical expressions for rays at less than the limiting angle, and by iteration (using RAYT) for rays crossing more than one layer in the profile. For each frequency attenuation factors are calculated in the form of beam patterns (amplitude vs. angle); these are analytic for rays below the limit angle and tabulated for rays above the limit angle. An array of flags is also produced for rapid determination (in INSTOR and CUSP) of which beam pattern type applies at each frequency.

PARAMETER INPUT

IPR Debugging print flag

COMMON INPUTS

/VELOC/	LHAX	No. of points in profile
	Z	Array (60) of profile depths, feet
	V	Array (60) of profile velocities, ft/sec

CRITA (Cont'd)

/INIT/	L	Index of source depth in profile
/RANGEL/	NFREQ	No. of frequencies
	IFOMIN	Index of lowest frequency
	FQ	Array (6) of frequencies, Hz
/PERIOD/	COSA	Limit angle for analytical beam patterns,
	angp ∫	radians, and its cosine
COMMON OU	TPUTS	
/CRIT/	BEE2	Coefficient of analytic low-frequency
		cut-off amplitudes
	Cl	Velocity at source (K1), ft/sec
	СХ	Velocity at profile axis, ft/sec
	JALF	All frequencies - analytical flag
	JAIF	Array (6) of individual analytical frequency
		flags
	CRITANX	Array (6) of critical angles vs. frequency
	CAX	Array (6,4) of beam pattern angles vs.
		frequency
	SS	Array (6,4) of beam pattern amplitudes vs.

frequency

SUBROUTINE RAYT

RAYT is called from CRITA to determine the relative phase (in terms of travel time) along a ray traced over one cycle, adjusted, if required, to account for surface and/or bottom reflections.

PARAMETER INPUTS

LA Index of source in velocity profile
COSTHO Cosine of initial ray angle

COMMON INPUTS

/VELOC/	LMAX	No. of points in velocity profile
	z	Array (60) of profile depths, feet
	c	Array (60) of profile velocities, ft/sec
/GRADS/	G	Array (60) of profile gradients, (sec 1)

'ARAMETER OUTPUT

CUTOFF Relative phase of ray, seconds

SUBROUTINE ANGSCH

ANGSCH is called from FACTTL to determine the families of rays to be processed, as a function of the sound velocity profile, and the source and receiver depths. Each family is chosen so that a smooth fit of ray range vs. ray angle can be made. Up to 100 rays in up to 20 families are allowed; if profile and source/receiver data cause these maxima to be exceeded, a diagnostic message is printed (on FORTRAN unit 6) and a flag is set to indicate this condition. The ray angles, in radians, are stored in a single array, THETA. The array IGRP is used to designate the index of the first ray in each family, and a second array, IGRAZE, indicates that the first ray in family just grazes a specified profile point.

The rays in each group are constrained to be at least three in number, with a maximum spacing of .5 degrees. A new family begins when a relative maximum in the profile is encountered, when either the surface or bottom is encountered, and when the profile gradient decreases by more than a specified increment.

COMMON INPUTS

/VELOC/	NPTS	No. of points in sound velocity profile
	Y	Array (60) of profile depths, feet
	С	Array (60) of profile velocities, ft/sec

ANGSCH (Cont'd)

/GRADS/ G Array (60) of profile gradients, (sec 1)

/INIT/ Kl Index of source depth in profile

K2 Index of receiver depth in profile

YML Mixing layer depth, feet

IMLP Index of mixing layer depth in profile

IML Index of mixing layer (as input)

/RAYZER/ THBINC Bottom angle increment (=50), radians

THETMB Critical angle for FNWC bottom type, radians

COMMON OUTPUTS

/RAYZER/ IRFFRZ Flag indicating grazing ray at K2

/CUSPCM/ ICUSP Flag indicating cusped caustic (turned off

if source and receiver within mixed layer)

/ANGLES/ NRAYS Number of rays in all families ≤ 100 or 999

NGRPS Number of families of rays ≤ 20

ISURF Index of first ray of hit surface

IBOT Index of first ray to hit bottom

IGRP Array (20) of indices of first ray in each family

IGRAZE Array (20) of grazing flags

THETA Array (100) of initial ray angles, radians

SUBROUTINE RANGER

RANGER is called from FACTTL, INSERT, and AXIS to compute the ranges associated with one up- and down-going cycle of a ray traced from the source depth (K1). The initial ray angle is positive if possible (source not at the surface) and is traced for a quarter-cycle, or until the ray hits the surface; the process is then repeated for a ray with negative angle if possible (source not at the bottom). As these rays are traced, RANGER calculates depth versus range; the crossings, if any, of the receiver depth (K2) are noted, and the corresponding ranges are saved.

The outputs from RANGER are the period of the ray, the maximum and minimum depths attained by the ray, and the distances to the first and second crossings of the receiver depth. If the receiver depth is not reached, these are instead the ranges to the first and second crossings of the source level, i.e., the half- and full-period ranges.

COMMON INPUTS

/VELOC/	NPTS	No. of points in sound velocity profile
	Y	Array (60) of profile depths, feet
	c	Array (60) of profile velocities, ft/sec
/GRADS/	G	Array (60) of profile gradients, (sec 1)
/INIT/	K1	Index of source depth

RANGER (Cont'd)

/INIT/ K2 Index of receiver depth

AK Vertex velocity of ray being traced, ft/sec

SINTHO Sine of initial ray angle at Kl

PARAMETER OUTPUTS

Rl Range of first crossing of receiver depth,

feet

R2 Range of second crossing of receiver depth,

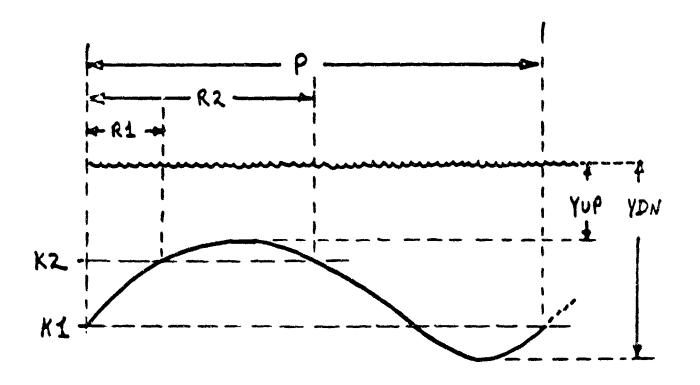
feet

P Full-cycle period of ray, feet

COMMON OUTPUTS

/PERIOD/ YUP Minimum depth attained by ray, feet

YDN Maximum depth attained by ray, feet



RANGER - Geometry for Ray Tracing

SUBROUTINE FITBOT

FITBOT is called by FACTTL to determine the coefficients of the fit of range vs. ray angle at the receiver (Θ_{K2}) for the last (bottom- and surface-reflecting) family. For rays with bottom angles less than 30° , the form of the fit is:

$$R = A(1) + A(2) \cdot (\theta_{K2} - \theta_{Min})^{\frac{1}{2}} + A(3) \cdot (\theta_{K2} - \theta_{Min})$$

For bottom angles greater than 30°, the form of the fit is:

$$R = \frac{1}{A(4) \cdot TAN(\Theta_{K2}) + A(5)}$$

All coefficients are calculated by FITBOT with the exception of A(4) which is calculated in FACTTL to give the correct limiting range for the (implicit) 90° ray. The derivatives of R vs. θ_{R2} are continuous at the value of θ_{K2} corresponding to the 30° bottom ray.

PARAMETER INPUTS

R Array (2) of ranges to be fit, feet

TH Array (2) of angles (at K2) to be fit, radians

A Array value [A(4)] of coefficient determined in FACTTL

PARAMETER OUTPUTS

A Array values [A(1), A(2), A(3), A(5)] of coefficients of fit of range vs. ray angle

SUBROUTINE FINDFT

FINDFT is called by FACTTL to determine the coefficients of the fit of ray range vs. ray angle at the receiver for all families except the last (bottom- and surface-reflected) family. The form of the fit is:

$$R = A(1) + A(2) + X(\Theta_{K2}) + A(3) + [X(\Theta_{K2})]^{2}$$

The form of the function $X(\theta_{K2})$ depends upon the value of IPAR:

IPAR = 1:
$$X(\theta_{K2}) = TAN(\theta_{K2})$$

IPAR = 2: $X(\theta_{K2}) = (\theta_{K2} - \theta_{Min})^{\frac{k_2}{2}}$

Three points are used in the fit: The minimum and maximum values of $\theta_{\rm K2}$, plus a third point which is the value of $\theta_{\rm K2}$ which gives a minimum or maximum value of range within the region of interest, or, if no minimum or maximum exists, the value of $\theta_{\rm K2}$ corresponding to the second ray in the family. For families with grazing rays at the receiver (Flag IREFRZ = 1), the three values of $\theta_{\rm K2}$ are 0, and the values $i\theta_{\rm K2}$ corresponding to the last ray in the family.

FINDFT also sets various parameters giving ranges in range, angle, and X, over which the fit of range vs. angle is valid. See the documentation of INSTOR for a diagram showing the notation employed (page 4-83).

FINDFT (Cont'd)

PARAMETER I	NPUT	
	IPRNT	Debugging print flag
COMMON INPU	TS	
/FLAGS/	C1C2	Ratio of source depth velocity to receiver
		depth velocity
/INPUTS/	KRAY	No. of rays in family being fit, \leq 100
	KP	Index of ray paths in array R, 1-4
	NORDER	Arrival order being processed
	NG	Index of family being fit, ≤ 20
	IPAR	Flag indicating functional form of fit
	R	Array '100,4) of ray ranges vs. source
		angle and path index, feet
	TH	Array (100) of ray source angles, radians
/INIT/	к1	Index of source depth
	к2	Index of receiver depth
/RAYZER/	IREFRZ	Flag indicating first ray grazes receiver
		depth
/CUSPCM/	ICUSP	Flag indicating cusped caustic
COMMON OUTF	PUTS	
/FLAGS/	THEIN	Angle at receiver of shallowest (at source)
		ray, redians
	THMAX	Angle at receiver of steepest (at source)
		ray, radians

Array (3) of receiver ray angles, radians

/FITS/ THF

FINDFT (Cont'd)

/FITS/ RF Array (3) of ranges of fit, feet

A Array (3) of coefficients of fit

XMIN Value of X(THMIN)

XMAX Value of X(THMAX)

RMIN Range corresponding to THMIN

RMAX Range corresponding to THMAX

RANMIN Minimum range spanned by fit, feet

SUBROUTINE FITQ

FITQ is called by FINDFT and CUSP to determine the coefficients of the quadratic function

$$Y = A(1) + A(2) \cdot X + A(3) \cdot X^{2}$$

which passes through the three points X(1),Y(1); X(2),Y(2); and X(3),Y(3), where $X(1) \neq X(2) \neq X(3) \neq X(1).$

PARAMETER INPUTS

X Array (3) of ordinate values

Y Array (3) of abscissa values

PARAMETER OUTPUTS

A Array (3) of coefficients of fit

SUBROUTINE INSTOR

INSTOR is called by FACTTL to add the intensity contributions arising from one arrival of one order of one family of rays to each applicable point in array TL over the range of interest. INSTOR is also called by CUSP to process any smooth caustic which may be associated with a cusped caustic.

The range interval is determined by the coefficients and parameters of the fit of range vs. (receiver) ray angle, calculated by FACTTL or CUSP and passed through common areas /FITS/ and /FLAGS/. The contribution of each arrival (which may actually represent several arrivals) at a given range point within this interval is subsequently added to the array TL by:

TL(Range, Freq) * TL(Range, Freq) * FACT/XL(Freq)

NI is the reciprocal ray intensity and is determined from one of four arrival geometries; FACT is a modifying factor (in the range 0-4) which accounts for the effects of in-, semi-, or fully-coherent combination of multiply-combined arrivals under the ICOH and IFLAG options. XI may also be modified to account for bottom-bounce losses and low-frequency cut-off effects.

The four arrival geometries and the corresponding reciprocal intensity factors are as follows. See relevant geometry diagrams on pages 4-83, 96 and 97.

1) Single-ray (no caustic) arrival:

XI(freq) = XIT1 = RANGE(K) & SIN1(1) & RP/COS2

where:

RANGE(K) = Range in feet, R

 $SINI(1) = |sin\theta_{K1}| (\theta_{K1} = ray angle at source)$

 $\cos 2 = |\cos \theta_{K2}| (\theta_{K2} = ray angle at receiver)$

RP = $|dR/d\theta_{K2}|$ at range R

2) Shadow zone of a smooth caustic:

XI(freq) = XIC(freq) *FAIRY(XAIR) *RANGE(K)/RC

Using:

XIC(freq) = XIC1*FREQ(freq)

xICl = CONST*SINCl*RC*(ABS(RPP**2/SINC))**

 $(1./3.)/\cos c$

XAIR - BETA(freq) DRAIR FACTOR

BETA(freq) - BETA1/FREO(freq) ++2

DRAIR = ABS (RC-RANGE (K))

FACTOR = 1./(COS(1.57079*ABS(DRAIR/(RCUT-RC)))), IRFG=1

· 1. IRFG-0

BETA1 = $(2. \cdot (SINC/5000.) \cdot \cdot \cdot 2/ABS(RPP)) \cdot \cdot \cdot (1./3.)$

whore:

RANGE(K) = Range in feet, R

RC - Range of caustic, feet

PREQ = (Radian frequency) -1/3

CONST =
$$C_{K2}^{1/3}/2^{5/3} \cdot ii$$
 · $Ai^2(0)$

SINC1 =
$$Sin\theta_{K1}$$
 (θ_{K1} is source angle corresponding

to
$$\theta_C = \theta_{K2}$$
 at caustic)

RPP =
$$d^2R/d\theta_{K2}^2$$
 evaluated at range RC

SINC = Sin
$$\theta_C$$

$$COSC = Cos \theta_C$$

FAIRY(X) = Modified Airy function
$$= [Ai(0)/Ai(-X)]^2$$

3) Illuminated region of a smooth caustic (no cusped caustic):

Using:

- 4) Illuminated region of a smooth caustic associated with a cusp:
 - a) Steep Branch ($|\theta_{K2}| \ge |\theta_C|$):
 XI(freq) is calculated as in 3) above
 - b) Shallow Branch ($|\theta_{K2}| < |\theta_C|$): XI(freq) = AMIN1(XI(freq), XICP)

Using:

XI(freq) = XIC(freq) *FAIRY(XAIR) *2. *RANGE(K)/RC

XICP - XICUSP(RANGE(K), 1000. • FREQK(freq)) • RANGE(K)/COS2

XIC(freq) is calculated as in 3) above

Where:

FREQK(freq) = Frequency in Hz

XICUSP(X) = Intensity Function - see CUSP, page 4-93

In addition to calculating the intensity contributions as citlined above, INSTOR determines when these are no longer significant, thus signaling the end of the loop on NORDER in FACTIL. This condition arises when the intensities fall below a minimum value, or when the range of an order is greater than the maximum range of interest. Flag IGTYP in common area /FLAGS/is set negative to indicate that this has occurred.

Arrival information (range, ray angle, and ray intensities at each frequency) is calculated and written on file IARVTP if this flag is not zero.

PARAMETER INPUTS

KRC Flag indicating arrival angle depth

SNTHR Sign of ray angle at depth flagged by KRC

IP Debugging print flag

IARVTP Flag indicating file for arrival information output

PARAMETER OUTPUTS

TL Array (250,6) of intensities vs. range and frequency

FILE OUTPUT

Unit IARVTP One record for each arrival angle at each range point. The format of each BCD record is as follows:

Position	Format	Contents
1	1H	Blank
2-7	F5.1	Range, Nautical Miles
8-9	2 X	Blank
10-16	F7.3	Arrival Angle, Degrees
17-18	2 X	Blank
19-23	F5.~1	Loss at 1st Frequency, dB
24-25	2 X	Blank
26-30	F5.1	Loss at 2nd Frequency, dB
etc	etc	etc
52-58	F5.1	Loss at 6th Frequency, dB

COMMON INPUTS

/FLAGS/	IGTYPP	Type of family (fit) being processed
	THMIN	Shallowest ray angle in family being processed
	THMAX	Steepest ray angle in family being processed
	CONST	Coefficient for caustic intensities

C1C2 Ratio of source velocity/receiver velocity CBC2 Ratio of bottom velocity/receiver velocity Flag indicating combination of arrivals ICOH IRSR Flag indicating surface-reflected rays MBOT No. of bottom bounces of family FNWC bottom type IBTYP IFLAG. Array (6) of coherency flags vs. frequency 11 F array (2,6) of semi-coherent phase factors vs. frequency Array (5) of coefficients of fit of R vs. 8 , FITS/ XMIN Minimum value of argument of fit XMAY Maximum value of argument of fit PMIN Fange of minimum-angle ray in family Range of maximum-angle ray in family RMAX RANMIN Minimum range at which intensities result , ilibitati KP Index of range of path being processed NORDER Order of arrival of path being processed /FANGEL/ NRANGE No. of range points NEREC No. of frequencies Index of minimum frequency IFOMIN FREU Array (6) of (radian frequencies) ** (-1/3) FREOK Array (6) of frequencies, KHz Array (250) of range points, feet RANGE /RAYZER/ IRFFRZ Flag indicating grazing arrival at receiver

/AUTCOH/	FNMIN	Min. no. of range points per surface- image cycle
		•
	FNMAX	Max. no. of range points per surface-
		image cycle
	FNXI	Reciprocal of FNMAX-FNMIN
	FNCYC	Array (2,6) of cycles of phase difference
		of up- and down-going rays at Kl and
		K2 vs. freq.
/CUSPCM/	ICUSP	Flag = 1 if processing smooth caustic
		associated with a cusp
/CRIT/	BEE2	Coefficient of analytic low-frequency
		cut-off amplitudes
	c1	Velocity at source (K1), ft/sec
	cx	Velocity at profile axis, ft/sec
	JALF	All-frequencies-analytical flag
	JAIF	Array (6) of individual analytical frequency
•		flags
	CRITANX	Array (6) of critical angles vs. frequency
	CAX	Array (6,4) of beam pattern angles vs.
		frequency
	SS	Array (6,4) of beam pattern amplitudes vs.
		frequency
/PERIOD/	PERO	Period of zero-degree ray at source, feet
	ANGP	Limit angle for analytical beam patterns
	IAXFG	Plag indicating source-receiver-axis geometry

COMMON OUTPUTS

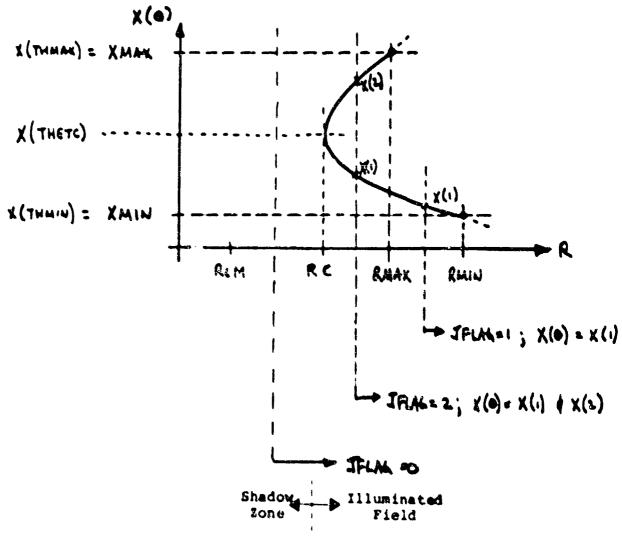
/FITS/ RANMIN Minimum range at which fit is applicable

FLAGE/ IGTYP! Set negative to indicate no contribution

to intensity

R is quadratic in $X_1(\Theta)$ or $X_2(\Theta)$ i.e., $R = A(1) + A(2) *X(\Theta) + A(3) *[X(\Theta)]^2$

$$X_1(\Theta) = TAN(\Theta)$$
 IPAR = 1
 $X_2(\Theta) = \Theta - \Theta_{Min}$ IPAR = 2



INSTOR - Fit of R vs. 0

NOTE: Throughout this figure $\theta = \theta_{K2} = Ray angle at receiver (K2)$

	-	,	SGN(I)			
ІСОН	SNTHR	NANG	1	2	3	4
O	(≠0)	4	SNTHP	-	1	_
	= 0	2	+1.	-1.	· •	
lor	# 0	2	SNTHR	SNTHR		: •
ţ	(=0)	4	-1.	-1.	+1.	-3.

INSTOR - Determination of No. of Arrival Angles and Their Signs

RCUT = FACTOR IN TABLE (N=NORDER) .PERO

IREFR2 = 1 so $KP \neq 3,4$

ICAUST

ICUSP = 0:

IAXFG = 1:

KP =

		-	2	3
	İ	(NONE)	(MIN RANGE)	(MAX RANGE)
	1	0	N	N+5
Î	2	0	N-1 ₂	Ŋ

IAXFG = 2:

 KP =
 1
 0
 N
 N+1

 2
 0
 N
 N+1

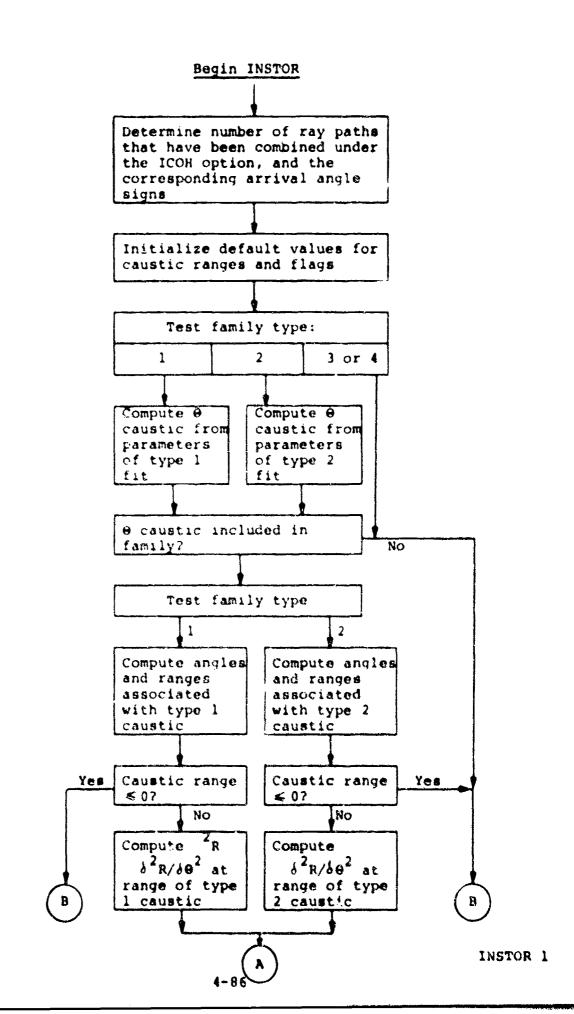
ICUSP = 1:

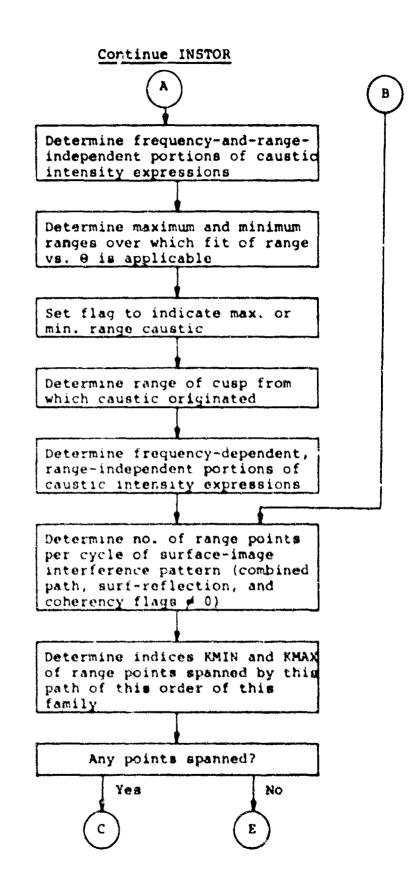
IRSR = 0 0 N-9 N+9

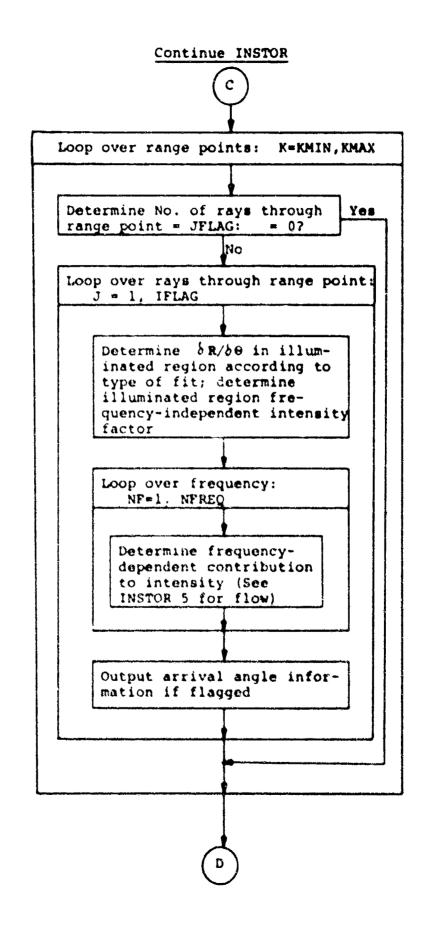
1 0 N-9 N+1

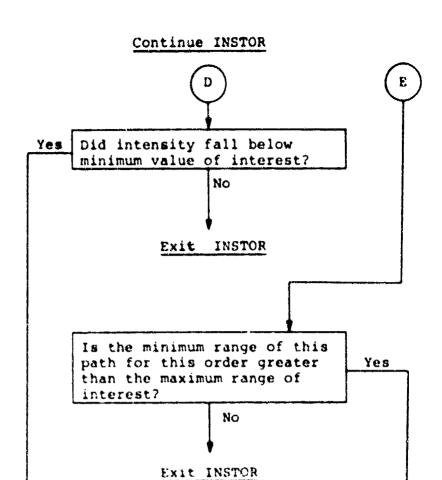
NOTE: RCUT = 0 if IREFRZ = 0

INSTOR - Determination of RCUT







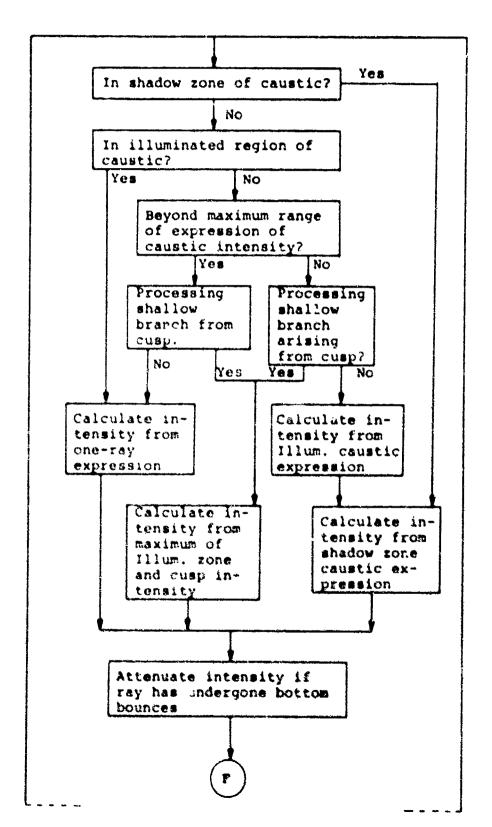


Set flag to indicate no intensity contribution made

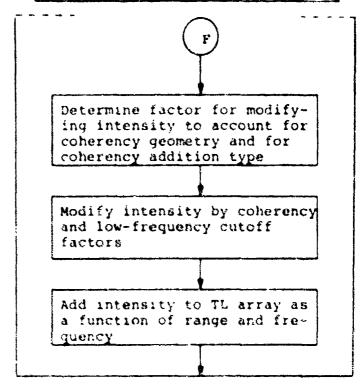
Exit INSTOR

by this path

INSTOR - Loop On Frequency



Continue INSTOR - Loop on frequency



SUBROUTINE CUSP

CUSP is called by FACTTL to add the intensity contributions arising from each order (other than direct) of a family containing a cusped caustic, to each applicable point in the array TL over the range of interest. CUSP also calls INSTOR to process any smooth caustic which may be associated with a cusped caustic.

The range interval is determined directly from ray path distances for the cusp itself; CUSP also calculates the coefficients and parameters of the fit of range vs. (receiver) ray angle for the smooth caustic (if any) which are passed through common area /FITS/ to INSTOR. For each range point in the interval covered, the intensity contribution to each frequency arising from one arrival order is added to the array TL by:

TL(Range, Freq) - TL(Range, Freq) + 1./XIP(Freq)

XIP is the reciprocal ray intensity and may be modified to account for bottom-bounce losses and low-frequency cutoff effects. It is computed from:

XIP(Freq) = XI(Freq) + RAN/CST

Using:

XI(Free) - XICUSP(IR, RAN, 1000. . PREQK(Preq))

CST - COS(THETA)

Where:

RAN - Range in feet, R

CUSP (Cont'd)

- THETA = Angle of ray at range R, estimated from

 linear or quadratic fit depending upon

 ray being processed.
- IR = 1 in one-ray region, 2 in three-ray region of cusp.

In addition to calculating cusp intensity contributions as outlined above, CUSP determines when these are no longer significant, thus signaling the end of the loop on NORDER in FACTIL. This condition arises when the intensities from the smooth caustics calculated by INSTOR fall below a minimum value, or when the range of an order is greater than the maximum range of interest.

Flag IDONE is set to indicate this condition.

Arrival information (range, ray angle, and ray intensities at each frequency) is calculated and written on file IARVTP if this flag is not zero.

PARAMETER INPUTS

- Kl Index of source depth
- X2 Index of receiver depth
- KRC Flag indicating arrival angle depth

CUSP (Cont'd)

IPRNT Debugging print flag

IARVTP Flag indicating file for arrival information output

PARAMETER OUTPUTS

Flag indicating end of contribution to intensities

Array (250,6) of intensities vs. range and

frequency

FILE OUTPUT

Unit TARVTP One record for each arrival angle at each range point. See INSTOR for format specifications.

COMMON INPUTS

/INPUTS/	N*	Number of rays in family
	R	Array (100,4) of ranges vs. ray angle and
		arrival, feet
	TH	Array (100) of ray angles of family, radians
/RANGEL/	NRANGE	No. of range points
	NFREQ	No. of frequencies
	FREQK	Array (6) of frequencies, KHs
	RANGE	Array (250) of ranges, feet
/PLAGS/	IGTYP	Type of family being processed
	NBOT	No. of bottom bounces at this order
	IBTYP	FNWC bottom type
/CUSPCN/	CCUSP	Velocity at cusp, ft/sec
/GRADS/	G	Array (60) of profile gradients, (acc)

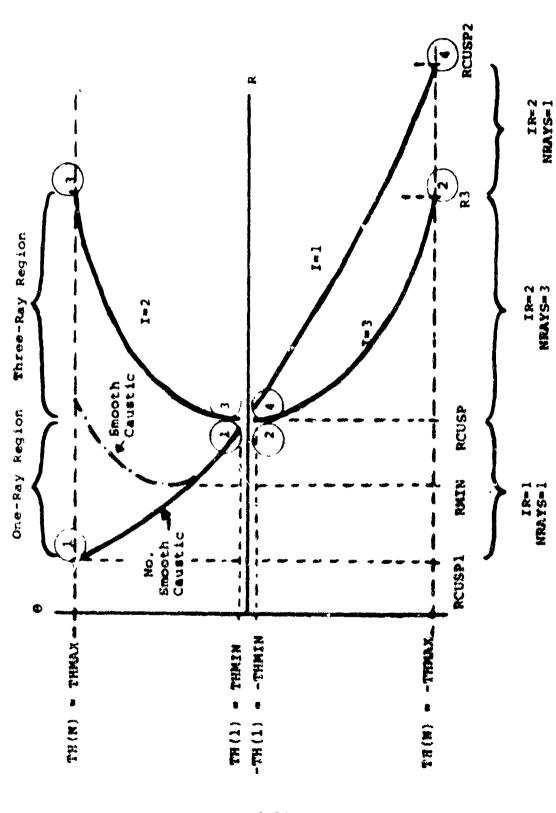
^{*}NRAYS elsewhere

CUSP (Contid)

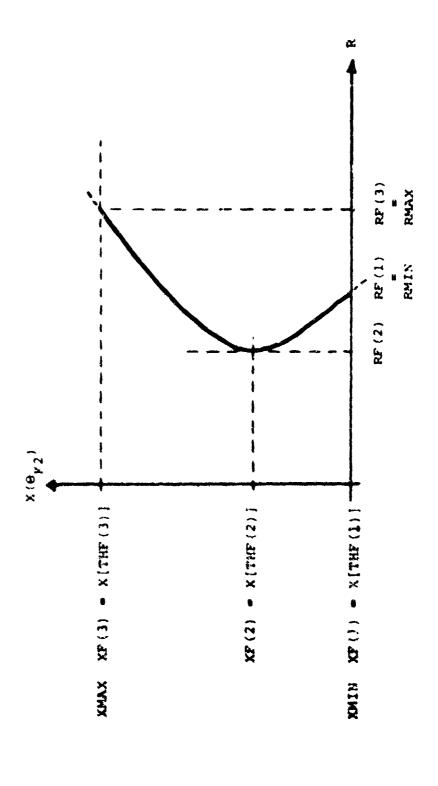
/PERIOD/	ANGP	Limit angle for low-frequency cutoff
/CRIT/	BEE2	Coefficient of low-frequency cut-off amplitudes
	c1	Velocity at source (K1), ft/sec
	CX	Velocity at profile axis, ft/sec
	JALF	All-frequencies-analytical flag
	JAIF	Array (6) of individual analytical frequency
		flags
	CRITANX	Array (6) of critical angles vs. frequency
	CAX	Array (6,4) of beam pattern angles vs.
		frequency
	SS	Array (6,4) of beam pattern amplitudes vs.
		frequency

COMMON OUTPUTS

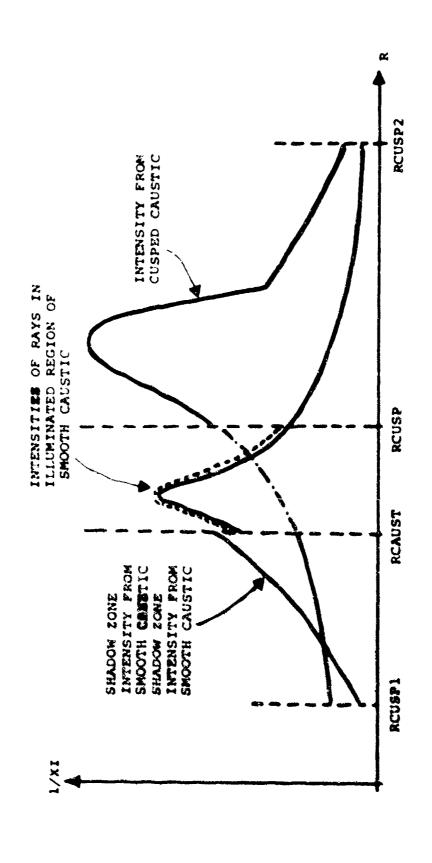
/FITS/	THF	Array (3) of angles of fit of R vs. 9 for
		smooth caustic, radians
	RF	Array (3) of ranges of fit, feet
	A	Array (3) of coefficients of fit
	XMIN	Minimum value of argument of fit
	XAMX	Maximum value of argument of fit
	RMIN	Range of minimum-angle ray in family
	RMAX	Range of maximum-angle ray in family
	RANMIN	Minimum range at which intensities result
/CUSPCM/	RCUSP	Range of cusp, feet
	BCUSP	Cusp parameter beta



1, 2) etc. refer to path subscript values in R (angle, path) array CUSP -- Fit OF R Vs. TH

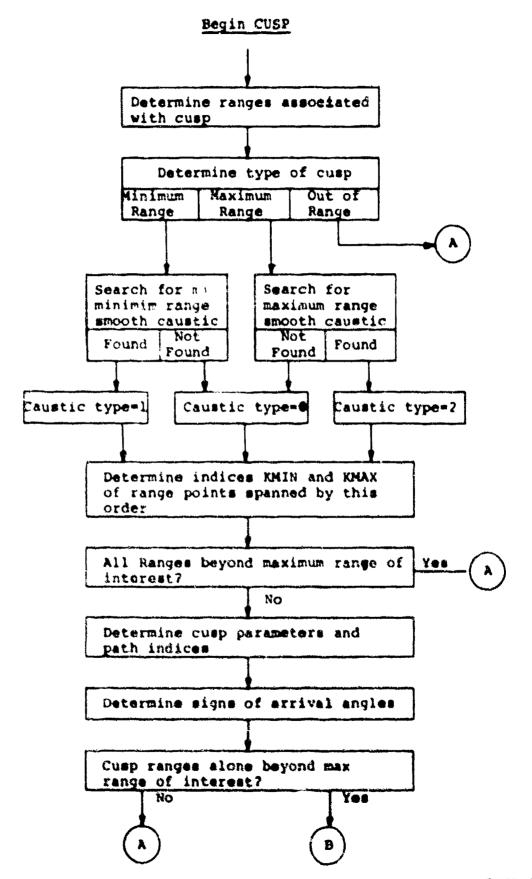


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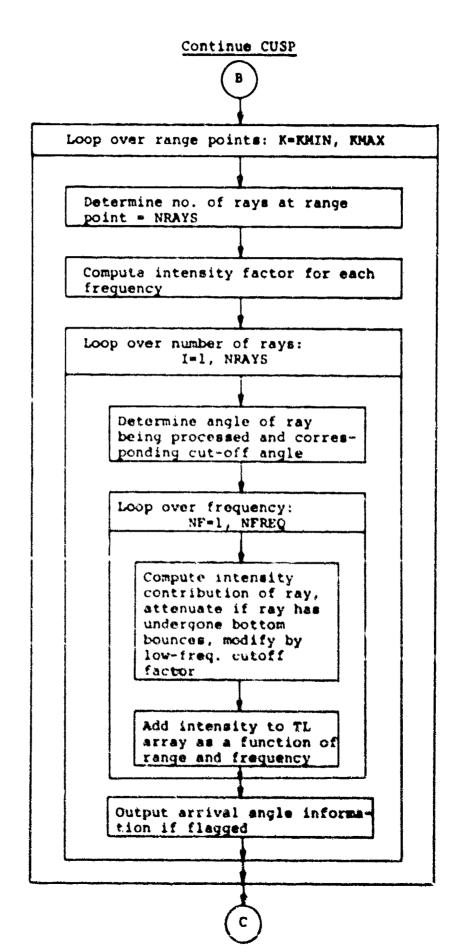


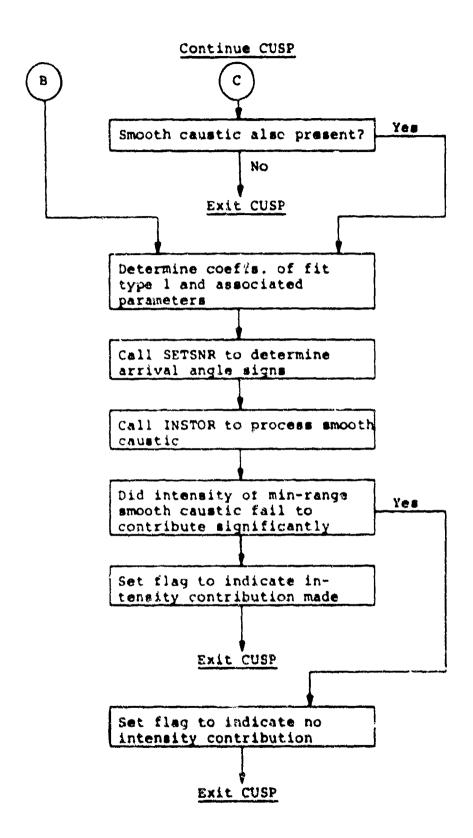
CUSP - Selection of Intensities in Region of CUSP With A Smooth Caustic

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SUBROUTINE HFCHTL

HFCHTL is called by FACTTL to calculate the intensities for other than direct and bottom-surface-reflected paths when the half-channel indicator has been set on input (index of mixing layer at bottom depth: IML = NPTS). The routine is strictly applicable only for three source/receiver depth combinations (60/60 feet, 200/300 feet, 200/60 feet) and frequencies (50, 300, 850, 1700 Hz). The computed intensities are proportional to 1/Range; the constant of proportionality is initially expressed as a transmission loss (dB re 1 foot) in the form:

 $TL = A - B \cdot \log (D/1000)$

where D is the half-channel depth in feet.

The coefficients A and B are each chosen from a separate 3x4 array as a function of source/receiver depth combination and of frequency. The coefficients in these arrays were themselves computed by FACT, using a temporary correction set to bypass the contributions to transmission loss arising from the direct and bottom-surface-reflecting paths. These FACT runs were made using a simple pressure-gradient profile (Avelocity/Adepth = .018 sec 1) to half-channel depths of 1000 and 18,000 feet.

PARAMETER INPUTS

NR No. of range points, ≤ 250

HFCHTL (Cont'd)

NPREQ No. of frequencies, ≤ 6

YS Source depth, feet

YR Receiver depth, feet

D Depth of half-channel, feet

FREQB Array (6) of frequencies, Hz

RANGE Array (250) of range points, feet

PARAMETER OUTPUTS

TL Array (250,6) to which intensities are added as a function of range and frequency.

SUBROUTINE QUAD

QUAD is called from INSTOR to solve the quadratic equation expressing R as a function of $X(\theta)$, in order to find the value(s) of $X(\theta)$ (and thus the value(s) of $X(\theta)$, if any, at the range point being processed in INSTOR. The roots are constrained to lie between XMIN = $X(\theta_{Min})$ and XMAX = $X(\theta_{Max})$. QUAD returns the number of roots = 0, 1 or 2, and the corresponding (ordered) values of $X(\theta)$. See diagram page 4-83.

The notation in QUAD

$$Y = A(1) + A(2) * X + A(3) * X * * 2$$

corresponds to

$$R = A(1) + A(2) * X(0) + A(3) * X(0) * * 2$$

in INSTOR.

PARAMETER INPUTS

A Array (3) of coefficients of fit

XMIN Minimum value allowable for X

XMAX Maximum value allowable for X

Y The range for which X values are desired

PARAMETER OUTPUTS

X Array (2) of solutions of equation

IFLAC No. of X values returned (0, 1 or 2)

FUNCTION SPEED

SPEED is called from INSERT to linearly interpolate in the sound velocity profile to determine the velocity corresponding to a source or receiver depth which has not been explicitly included as a point on the input profile. The results are unpredictable if this depth is less than the minimum profile depth; the last segment of the profile is linearly extrapolated for a depth greater than the maximum profile depth.

PARAMETER INPUT

YP Depth at which velocity is to be determined, feet

COMMON INPUT

/VELOCX/	NPTS	No. of points on profile
	Y	Array (60) of profile depths, feet
	С	Array (60) of profile velocities, ft/sec

FUNCTION OUTPUT

SPEED Interpolated value of velocity at depth YP, ft/sec

FUNCTION SETSNR

SETSNR is called from FACTTL and CUSP to determine the sign(s) of the arrival angle(s) at the depth at which arrival information is being determined. It returns the sign(s) of the angle of the ray(s) corresponding to the path of interest, which may be multiple, according to the coherency option in effect.

If KRC = 1, the sign of the angle(s) at depth K1 is returned; if KRC = 2, the sign of the angle(s) at depth K2 is returned.

A value of 0. is returned to indicate that both up— and down—going rays (signs = +1. and -1.) are present.

PARAMETER INPUIS

ICOH Coherency option in effect - 0,1,2 or 3

KRC Flag indicating arrival depth

Kl Index of source depth

K2 Index of receiver depth

KP Index of path being processed

FUNCTION OUTPUT

SETSNR Sign(s) of arrival angles: +1., -1., 0.

See below for values returned as a function of input parameters.

KRC = 0:

0.

KRC = 1:

		K	P	
ІСОН	1	2	3_	4
0	1.	-1.	1.	-1.
1	0.	0.	0.	0.
2	1.	-1.	1.	-1.
3	0.	0.	0.	0.

KRC = 2:

(K1 Deeper Than K2)

1		K	P	
ІСОН	1	2	3	4
0	-1.	-1.	+1.	+1.
1	-1.	-1.	+1.	+1.
2	0.	Ο.	0.	0.
3	0.	0.	0.	0.

KRC = 2:

(K2 Deaper Than K1)

		k	P	
ICOH	1	2	3	4
C	+).	+1.	-1.	-1.
1	+1.	+1.	-1.	-1.
2	0.	0.	0.	0.
3	0.	0.	0.	0.

SETSNR - Function Value Returned

FUNCTION FAIRY

FAIRY is called by INSTOR as a step in calculating the intensities which exist in the neighborhood of a smooth caustic. The function is related to the Airy function (for real arguments) as follows:

FAIRY (X) =
$$\left[\frac{Ai(0)}{Ai(-X)}\right]^2$$
 -1.77 \leq -x \leq 4.0
= $\left[\frac{Ai(0)}{Ai(-4)}\right]$ x < -4.0
= .792 \cdot (x)^{1/2} x > 1.77

The function is approximated over the primary range of interest by 10.**CX, where CX is interpolated from tabulated values of C(I) vs. I; these values are:

$$C(I) = 2\log_{10} \left[\frac{Ai(0)}{Ai(\frac{I-11}{5})} \right] \qquad I = 1(1)31$$

This range of I corresponds to -X ranging from -2. to +4. at intervals of 0.2.

PARAMETER INPUT

X Argument of function

FUNCTION OUTPUT

FAIRY Functional value corresponding to X

FUNCTION XICUSP

XICUSP is called by CUSP and INSTOR as a step in calculating the intensities which exist in the neighborhood of a cusped caustic. The function computes the vertical spreading near the cusp, returning the single-path value assuming three equal-amplitude paths in the interference (three-ray) region and one path in the one-ray region.

The calculation is three-step:

1)
$$X = \left[\frac{3 \cdot W}{C}\right]^{1/2}$$

where:

8 = Cusp parameter

W = Radian frequency

C = Cusp sound velocity

$$Y = f\{\pm (R-R_C) + X\}$$

where:

R = Range of interest, feet

Rc - Range of cusp, feet

f is calculated by call to function FE2B. The sign of the argument is positive in the one-ray region, negative in the three-ray region.

3) XICUSP = 77/(X · Y)

PARAMETER INPUTS

IR Flag indicating one- or three-ray region

RAN Range of interest, feet

FREQ Frequency, Hz

XICUSP (Cont'd)

FUNCTION OUTPUT

XICUSP

Functional value of spreading

FUNCTION PEZB

PE28 is called from XICUSP to calculate the Pearceyfunction component of the expression for vertical spreading in the vicinity of a cusp. The function is related to the Pearcey function as follows:

PE2B(y) =
$$\pi r/-y$$
 $y \le -3.5$
= $\frac{Pe(y)}{3}$ $-3.5 \le y \le 0$
= $Pe(y)$ $0. \le y \le 2.0$

The function Pe(y) is approximated over the primary range of interest by P**2, where P is interpolated from tabulated values of PT(I) vs. I; I = 1(1)23. This range of I corresponds to y ranging from -3.5 to 2.0 at intervals of 0.25.

PARAMETER INPUT

Y Argument of function

FUNCTION OUTPUT

PE2B Functional value corresponding to y

FUNCTION THBOT

THBOT is called by INSTOR and CUSP to determine the ray angle at the bottom as a function of the ray angle at the receiver depth. This angle is determined from linear interpolation in the values of bottom angle vs. receiver ray angle as previously tabulated by routine TABTH2.

PARAMETER INPUTS

TH2

Ray angle at receiver depth (K2)

COMMON INPUTS

/TH2TAB/	TH2MIN	Minimum ray angle at receiver depth
	FACTOR	Reciprocal of increment of TH2T values
	TH2T	Array (21) of ray angles at receiver depth
	THBT	Array (21) of ray angles at the bottom
	RATIO	Array (20) of ratio of increments of
		TH2T to increment of THBT

FUNCTION OUTPUT

THBOT Interpolated value of bottom angle

FUNCTION BOTTOM

BOTTOM is called from INSTOR and CUSP to calculate the intensity attenuation occurring along bottom-bounce ray paths. The attenuation is returned as a value between 0 and 1. Currently, BOTTOM returns a 1 (no attenuation) if the input bottom type is 0, and calls upon FNWC routine BTMLOS for bottom types 1-9. This routine may be replaced or restructured according to the desires of the FACT user.

PARAMETER INDUTS

NBOT No. of bottom bounces

IBTYP Bottom type, 0-9

THB Ray angle at bottom, radians

FREQ Frequency, Hz

FUNCTION OUTPUTS

BOTTOM Bottom attenuation

5. THE FACT HANDOUT

The following pages contain a reproduction of the AESD FACT Handout, a computer-maintained document which is an integral part of the FACT Package. The various sections are as follows:

- A description of the physical basis of the FACT Model;
- A description of the computer program flow;
- A description of the FACT Package Program Library;
- A description of the input card formats accepted by the TLOSS program;
- A description of the input deck structure;
- A listing of a sample set of input data cards;
- The outputs resulting from this input deck;
- The listing produced by a CDC 6600 FORTRAN compilation of FACT.

Of the last section, only the listing of the program TLOSS is included in this report.

FAST ASTHPTOTIC COMERENT TRANSMISSION (FACT) MODEL

DE VELOPED BY

ACOUSTIC ENTINONPENTAL SUPPORT DETACHMENT

OFFICE OF NAVAL RESEARCH

1 APRIL 1973

MIGHER DEDEK FACT MODEL IS A RAV ACOUSTIC MODEL MMICH UTILITES THE RESURPTIONS OF RAY ACOUSTICS APE LIMITIMS. THE PRINCIPAL INPROVENENTS OF THE FACT PROCERM ARE AS FOLLOWS --

EXPRESSIONS OF MAY ACOUSTICS ARE DISCAMPED BY THE CLASSICAL THEY PREDICT INFINITE INTENSITY, MATHEW, THE FIELD NEW THE CAUSTIC IS EVALUATED USING THE APPROPRIATE ASYMPTOTIC EXPRESSIONS FOR THE PARTICULAR TYPE OF CAUSTIC-

1. SHOOTH CAUSTICS (2-RAY SYSTEMS) - BREKHOVSKIKH'S EXPRESSIONS.
2. CUSPED CAUSTICS (3-RAY SYSTEMS) FOR SOURCE AND RECEIVER AT THE SAME DEPTH - LUGHIG'S EXPRESSIONS.
3. COMBINED SHOOTH AND CUSPED CAUSTICS (4-RAY SYSTEMS). THE RHS SUM OF THE SHOOTH AND CUSPED-CAUSTIC FIELDS.

CAUSTIC FIELDS ARE EXTENDED INTO THE SHADOW ZONE TO THE RANGE OF THE CUSP WHERE THE SHOOTH CAUSTIC ORIGINATED.

BY A "SENI-COMERRY" ADDITION OF ARRIVALS. FOR SHALLOW SOURCES AND/ON RECEIVERS THE PATHS WITHIN AN ARRIVAL ORDER WHICH DIFFER ONLY BY A SURFACE REFLECTION AT THE SOURCE (AND RECEIVER) HAVE PREDICTARLE PHASE DIFFERENCES BETWEN OIFFRENCES BETWEN OIFFRENCES BETWEN OIFFRENCES BETWEN OIFFRENCES BETWEN OIFFRENCES BETWEN OIFFRENCES OF PHASED SUMMATION OF THE RESULTING SETS. AS THE RATE IN THE OSCILLATIONS OF A PARTICULA COMERCY SUMMATION INCREASES THE RANGE CRIC MAY BECOME TO COMERCY SUMMATION SAMPLE THE OSCILLATIONS OF A PARTICULA COMERCY SUMMATION SAMPLE THE OSCILLATIONS. BUEN THIS COURSE TO ADEOLATELY SAMPLE THE OSCILLATIONS. BUEN THIS COURSE THE SUMMATION IS PERFORED MITM AN EFFECTIVELY REDUCED COMERCICE UNTIL FOR VERY COARSE CRIOS ALL PATHS ARE SUMMED INCOMERCILLY.

ANIS-TO-ANIS TRANSMISSION IS TREATED IN THE FOLLOWING MAY.

THE PEDIOD OF THE ANIAL RAY IS COMPUTED FOR THE SHOOTH PROFILE

CORPESSONDING TO THE LINEARLY SEGMENTED FORTILE. THE RAY WITH

THE SAME PERIOD WHEN TRACED IN THE LINEARLY SEGMENTED PROFILE

IS COUND AND FHE DIPPHS OF ITS MORIZONTAL TURNING POINTS ARE

FIFTH AND THE SOUTH FOUNDED AND MESTIVEN THE NET FEFECT OF THIS

WHICH MOULD OCCUR FOR THE ANIAL—RAY FAMILY IN THE COULVALENT

SHOOTH PROFILE.

A MES PHASE-INTEGRAL TECHNIQUE IS USED TO REDUCE THE INTENSITY RAY—EQUIVALENT OF THE FIRST NORML MODE. THIS SIMULATES LOM-FREDUCKOF CUT-OFF EFFECTS ON RAYS WHICH CYCLE MITH WENTICAL MPHILIDDES WHICH ARE SHALL IN TERMS OF MAYENGENES.

ASTER DEPTHS OF LESS THAN 1000 FEET, AND FPEDUE MCVFDOTTOM CLASS COMPINATIONS WHERE BAYS STRIKING THE BOTTOM AT LESS THAN CRITICAL SOUTHWATER WO PELLESS THAN CRITICAL CURVE IS A SHOOTHED APPROXIMATION TO THE CURVE CENERATED IN THE FACT MODEL AND PEDUIPES COMSIDERABLY LESS COMPUTATION TIME. FOR ASSAMP PURPOSES THE SHALLOW MAKER HODEL IS ALWAYS USED WHERE

A MALF CHANNEL MCDEL MAS ALSO BEEN INCLUDED SPECIFICALLY FOR ASRAP PURPOSES. FOR THE PARTICULAR SOURCE DEPTHS AND FREQUENCIES USED IN ASRAP HALF-CHANNEL CASES THE INTENSITY DUE TO RSR PAINS IS APPROXIMATED BY A CURVE OF THE FORM OF

TL + A + 10 * L26 (R)

MMERE A IS A FUNCTION OF THE SOURCE AND RECEIVER DEPRMS, THE
FREDUENCY, AND THE BOTTOM DEPTM, AGAIN THIS CURVE APPROXIMATES
THE MORMAL FAST RESULT, HOMEVER, TAKES CONSIDERABLY LESS CCHPUTER
THE, FOR ASSAR THIS IS ALMAYS USED WHERE APPROPRIATE, FOR
GENERAL USERS IT MILL DE INVOKED WHEN THE MINED LAYER DEPTM IS
SET TO THE ROTTOM, HOMEVER UMESS THE SOURCE AND RECEIVER DEPTMS
AND FREDUENCIES CORPESPOND TO ASRAP CASES IT SHOURD DE ANDIDED.
FINALLY, THE BASIC TRANSMISION LOSS PROCRAM (EXCLUDING THE SHALLON-MATER AND MALF
CHANNEL APPROXIMATIONS) MAY BE USED TO OBTAIN ARMINAL STRUCTURE AS FOLLONS. FOR CONTRINING -

RANCE, AMCLE, (TL (I), I'e1, MFREG) (FORMAT BF18.3)

UNICH MAY BE USED FOR LATER COMPUTATIONS. THE ANGLE (RANGE) CURVE IS ALSO PLOTTED (ON THE LINE PRINTER).

FACT MODEL PROCRESS FLOW

THIS SPOTION OF SCOTING THE PROCESS FLOW IN THE TRANSMISSICH LOSS MODULE (SUBPOUTING FACTIL), THE OTHER DECKS, TLOSS, ETC. ARE MERCLY DRIVER PROCRAWS TO CALL FACTIL,

FACTTL -

- INITIALITATION OF VARIABLES AND APPAYS
- CALL INSPAT
- MAKES SPACETORL EAPTH CORRECTIONS ON PROFILE AND SOURCE AND RECEIVER
 - COMPUTES STATO LAVER AND THERMOCLINE GRADIENTS FOR SURFACE DUCT CALCULATION (IF APPLICABLE)
- CALL ARIS

.

- COMPUTES PERIOD OF ZERO-PEGREE RAY ALONS ANIS OF SMOOTHED FOULVALFHY PROFILE AND HOVES SOURCE AND PECETVED IT MELESSAPY) TO SIMULATE ANIS-TO-ANIS
- 124m5m15510m. - COMPUTES LIMITING ANGLE FOR SUBSECUENT PHASE INTEGRAL FAITH ATTOMS
 - CALCULATIONS. INSERTS SOUTH PROFILE MOVING THEM
- SLIGHTLY OF CHANCING SOUND SPEEDS SLIGHTLY TO PREVENT THEM FROM MANING THE SAME SOUND SPEED.

 COMPUTES INFORMATION MFERS FOR SUBSEQUENT LOCATION OF THE CUSPS FROM MMICH SMOOTH CAUSTICS IN THE FIRST FAMILY OF RAYS OFFICINATE.
- FAMILY JF GAYS ORIGINATE.
 COMPUTATION OF FREQUENCY-TEPENDENT FACTOR FOR CONTRENCE.
 ASSORPTION. AND SURFACE DUCIS.
- CALL TABTH2
- TABULATES THE GAY ANGLE AT THE BOTTOM IN TERMS OF THE ANGLE AT EITHER THE SOURCE OR RECEIVER DEPTH (MAICH!VER MAS A MIGHER SOUND SPEED).
- CALL CRITA
- COMPUTES WES PMASE FACTORS FOR LOW-FREGUENCY CUT-OFF EFFECTS.
- CALL AMESON
- DETERMNES RAYS TO BE TRACEO AND DEFINES RAY FANILIES WITHIN WHICH INTERPOLATIONS ARE WALLD IN A SMOOTHED ANGLE VERSUS RANGE CURVE.

FOOD ON FACH FATTE

- Aliets to are mury of a diving little
- Cholis the itals of there the Culose tilence APPIVALS OF UPCOING DAV.
- COAPUTE SEMI-COMFRENT PARSE FACTORS FOR THIS FAMILY.
- CADUR ARRIVALS FOR COMPRENT CONTINETION OR IF CLOSE ENDUCH IN BANGE TO BE CONSTDERED INENTICAL. THE MINAGE OF REGISTER WAY THEN BE PEDUCED FROM THE USUAL FOUR TO TWO OR ONE MITH CORPESSED ON THE USUAL FOUR TO TWO OR ONE MITH
- PROCESS Each ormaining approal in successive approal of DE 25 unit, the family tand its naustic shadow zone filting has excepted interest.
- FOR STEEPEST RAY FAMILY INSTINS-PERLICTED SURFACE-REFLECTED) CALL FITHOT
- TO RITHETAL USING MIMIMUM MAY, PAY AT COTTICAL AMOLE OF LOS PREDUCYCY MOTTOM-PEFLECTION COEFICIENT, AND IMPLICITELY NO-DEGREE MAY. COMPUTES PARAMETERS OF FIVE COFFFICIENT FIT
- FOR SMALLOWER FAMILIES CALL FINDER
- THETA-THETANTH) FOR RETHETAL THROUGH BOUNDING ANGLES OF FAMILY AND MIN TOR MAY RANGE POINT FITS A QUAPPATIC IN EITHER TANITMETA) OF SORT IN FAPILT .
- CALL INSTOR IF FAMILY DOES NOT CONTAIN CUSPED CAUSTICS

•

- COMPUTES THE INTERSITY CONTRIBUTION FROM THE FAPILY AT FACH RANGE POINT.
- CAUSTIC PARAMETERS AND FIELDS ARE COMPUTES AS WELL AS ALL SENI-COMEPENT FACTORS AND BOTTOM-PEFLECTION LOSSES.
- CALL CUSP FOR FAMILIES MITH GUSPED CAUSTICS

•

- COMPUTES FAMILY PARAMETERS AND CUSPED CAUSTIC COPPECTIONS.
- CALLS HIGUSP TO COMPUTE GUSPED CAUSTIC FIELDS. ADDS IN BOTTOM REFLECTION LOSS IF ANY. FOR FOUR RAY SYSTEMS CALLS INSTOR TO COMPUTE SHOOTH CAUSTIC CONTRIBUTION.

END PROCESSING OF A FANILY, GO TO NEXT FANILY •

ADD TH MAINTERNMEN MOM MOTTOM-MEFLECTED CONTRIBUTION (FOR ASSET ITT MAIN CHANNET CASTS ONLY)

ADD IN BUCKED CONTRIBUTION

CONVERT TO TLOSSIBLED. CINCLUDING VOLUME ASSORPTIONS

RETURN

FIRE FACT PACKAGE PROCESS LIBERAY CONTAINS ALL FORTRAN ROUTLINGS BEGUNEED TO INVESTME THE FACT ACCOSTIC RODEL. THE PROCESS INSERT CONFORMETS ARE AS FOLLOWS...

MAINPROGRAM PLOSS -- READS CARD INPUTS, COMPUTES LOSSES THRU SUBROUTINE CALLS, AND PRINTS AND/OR PLOTS (ON THE PRINTER) THE RESULTS.

SUPPOUTINE FACTIL--THE FACT WAY TRACING MODEL
SUPPOLITIVE SHALTL--A SIMPLIFIC MODEL FOR SHALLOW MATER,
CALLED INSTEAD OF FACTIL BY AUTOIL
UNDER CFPTAIN CONDITIONS.
SUPPLINE MFCHTL--A SIMPLIFIC HANNEL MODEL, USED BY FACTIL

THE FACT MODEL SUPROUTINE FACTTL REQUIRES

IN COMMUTATIONAL SUBROUTINES... INSERT AXIS

CRITA RAYT
RANGER FITOT

FITO INSTOR

GUAD

FITO XICUSP PEZE

BOTTOM BYTELOS

FINDUTAMO OUTPUT SUBROUTINES...

SIMPUT AMD OUTPUT SUBROUTINES...

TAMES

TAME

TABTHZ ANGSCH FINDFT EUSP

TO MAKE AN DEJECT PROCRAN FOR THE CARD INPUT PROCRAN TLOSS. ALL COMPONENTS MITH THE EXCEPTION OF AUTOIL AND SHALT, SHOULD BE COMPILED. THE PESULTING PROCRAN OCCUPIES APPROXIMATELY ANGRE FOCTALE WORDS ON THE COC GABS.

A ott

FATER

IN THE CODE 6688) FACT PACKAGE PROGRAM LIGHARY. THE FOLLOWING CONVENTIONS HAVE BEEN FOLLOWED.... EACH DECK IS A SIMULE PROGRAM, ROUTINE, OR FUNCTION.
THE DECK MAME IS IDENTICAL TO THE MOUTINE MAME.
ALL DECKS ARE SEQUENCED MITHOUT CORRECTIONS.

THE CARD INFUTS TO TLOCK ARE DETAILED IN THE COMMENTS WITHING FIRE PROCESS, AND REPEATED WITH FOR BEFERENCE PURPOSES.

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WAR TO THE

F 500 F F F F F F F F F F F F F F F F F	615 8610.2 3168.2.86.2.66.23 6518.2 8718.2.619	
3474 11716 11716 803 PURI	# : [. [P .] M .] M .] M .] 2	FACTIL CALLED TO COMPUTE LOSSES LOSSES PPINTED AND/OF PLOTTED
C 4 29		# # # # # # # # # # # # # # # # # # #

" IS NO. OF PPOFILE PRINTS - 2.LE. (ABSINI).LE. 50

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15085 TO READ CARD

*FOD & POSITIVE, BEDFILE IS TABLIT DIPLITY IN DEPTH, VELOCITY PAIRS, */CAPO, A VELOCITY .LT. MORGIN IS USED AS AN INDICATOR OF METRIC IMPUT (M,M PER S) 90TM DEPTHS * VELOCITIES AS CONVENTED TO ENGLISH UNITS (FILET PER SEC).

*FOR A MEGATIVE, PROFILE IS INDUT AS DEPTH, TEMP., SALINITY TRIPLETS, 3/CAMO, METRIC UNITS ARE ASSUMED (M.CEMT.PRIP. MILSOMS FORMULA IS USEN TO COMPUTE VELOCITIES, DEPTHS * VELOCITIES ARE THEN COMVERTED TO ENGLISM UNITS.

* THE IMPOT PROFILE IS ALMAYS PRINTED, IF CALCULATIONS . CONVERSIONS ARE REQUIRED, THE RESULTING VALUES ARE ALSO PRINTED.

THE COTTOM MEPTH IS ALMBYS PINI

TL IS THE INDER OF THE HIND LAYFO DEPTH IN THE IMPUT POOFILE ESPARATED COMPUTATIONS AND THEN PERFORMED FOR A SUPFRECE DUCT OF THIS OTHERSION AND NO DAYS ARE TRACED IN THE DUCT). EITHER IS OF 3 CAN PR. USED TO INDICATE THAT NO LAYER IS PRESENT. 4 LE. IL. LE. (ABSIN)). IL # (ABSIN)) INDICATES THAT A MALE-CHANNEL CONDITION IS PRESENT AND THAT THE ROUTINE MYCHIL ROOMALLY USED ONLY FOR ASRAP! SHOULD BE USED.

18 IS THE GOTTON TYPE
A NEGATIVE VALUE INDICATES THAT THE USER WILL SUPPLY A BOTTON LOS
FUNCTION, AND MODIFY FUNCTION BOTTON TO CALL THE REPLACEMENT FOR
THE DEFAULT FUNCTION NIMLOS.
1-9 INDICATES FING BOTTON LOSS FUNCTIONS

IN IS THE MAYE MEICHT IN FEET

-1. POINT AND PLOT (*G PLUS -1)

IAP (S THE AMMINAL CALCULATION INDICATOR

9. N LAPPINES

NO IS THE NUMBER OF RANGE POINTS I LE. NR LE. 250

1.. spotest awars us, mance calculated and plotted

OF IS FAR INCREAFAIAL (AND FIRST) PRINCE IN N. MI.

FILL BRE THE PREGUENCIES - UP TO SIX - IN WERTZ.

TE THE SOURCE DEPTH IN FEET.

A IS THE RECEIVER DEPTH IN FEET.

*IF EITHER SOURCE OR RECEIVER DEPIM IS OUTSIDE THE PROFILE LIMITS (LESS THAM ZERO OR GREATER THAM ZERO) THE SOURCE OF RECEIVER IS BOTTOMED.

#CEF) ARE THE COMERENCE INDICATORS, AND CORRESPOND TO THE FELDS 1-TO-1

1 * 1450MEZENCE

2 * FULL COMERENCE

*THE VALUES OF JOILS ARE MORNALLY LEFT BLANK TO INDICATE THAT SEMI-COMERENCE IS TO BE USED FOR ALL FREQUENCIES.

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2012-77 7486

THE RESULTS AME PRESENTED IN ANY ONE OF FIME OUTPUT FORMATS. DEPENDING ON THE PRESENTER AS SPECIFIED ON THE TYPE FORTAL CAND STATESER VARIABLE IPLE.

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THE FIRST DATA PRINTED IS THE TITLE CARD.

THE SECOND DATA PRINTED VEHIFIES THE INPLY PARAMETERS AS FOLIOMS --

FIRST, MP. IL. IM. AMO IN AME PRINTED. SECOND, ALL THE IMPUT FALJES OF DEPTH AND FELDCITY OR TEMP.-SALINITY ARE PRINTED, PLUS ANY CONFESIONS MADE.

THIST, THE BANGE AND INCREMENT PARAMETERS BEING USED ARE PRINTED.

POUGHTS, FACT PRINTS ALL FREQUENCIES SEING CONSIDERED AND THE

COMEMENCE OFFICH--

1034 · 1

LIP TO THIS POINT, FACT MAS PRINTED OMIT DATA VALUES, TO ALLOW FOR VERIFICATION AND WEFFRENCE USE.

FACT MILL WOM PRINT CCMPUTED RESULTS. THERE ARE THO RESULT
LISTIMOS AVAILABLE -- (1) A TABLE OF TRANSMISSION LOSSES, AND (2) A GRAPH
OF THANSMISSION LOSSES (AND ARRIVAL STRUCTURE WHEN APPROPRIATE). WHETHER
FACT WILL PRINT ONLY THE FIRST, ONLY THE SECOND, DR BOTH DEPENDS ON WHAT IPL
PARAMETER HAS SPECIFIED ON THE TYPE 2 DATA CARD. THREE SAMPLE CASES ARE
GIVEN BELOW TO ILLUSTRATE THE TYPES OF OUTPUT AND FOR REFERENCE PURPOSES
IN COMPERTING FACT DECKS TO OTHER SYSTEMS/COMPUTERS.

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MAN MO. 1 PMESSUGE 4776.00 12000.00 1	3		-	
SAMULE MUM NO. 1 PMESSUGE 1000.00 170.00 1200.00 1000.00 170.00 200.00 120.00 150.00 120.00 150.00 -				
	GABLIENI PROFILE. AMRIVAL STRUCTURE COMPUTED.	AHRIVAL SI	AUCT URE	COMPUTED.
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#ACT SAMPLE 734 NO. 1 -- PRESSURE GRADIENT PROFILE, ARRIVAL STRUCTURE COMPUTED.

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16.50.22 09/27/76 PACT SAIPLE BUR HO. 1 -- PRESSURE GRADSENT PROFILE, ABRICAL STRUCTURE COMPUTED. 40CF1468 06074 . 7288,8 FT thrace state .

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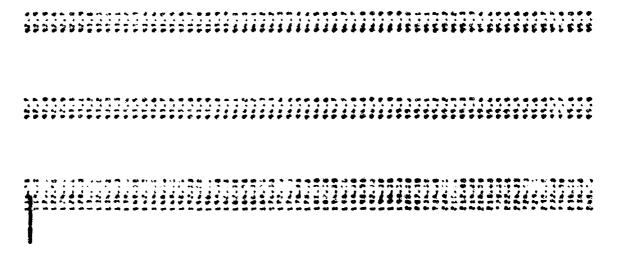
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- 1. In accordance with reference (a), a declassification review has been conducted on a number of classified LRAPP documents.
- 2. The LRAPP documents listed in enclosure (1) have been downgraded to UNCLASSIFIED and have been approved for public release. These documents should be remarked as follows:

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Unavailable	Cornyn, J. J., et al.	TION. VOLUME 2. MODEL EDEX DATA	Naval Research Laboratory	740701	AD0530983	U
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